

The Mesicopter

A Meso-Scale Flight Vehicle for Atmospheric Research

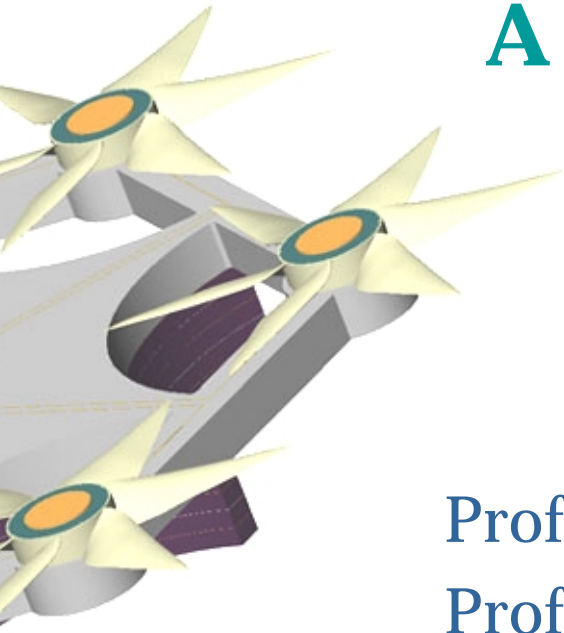
Stanford University

Prof. Ilan Kroo, Dept. of Aero/Astro

Prof. Fritz Prinz, Dept. of Mech. Eng.

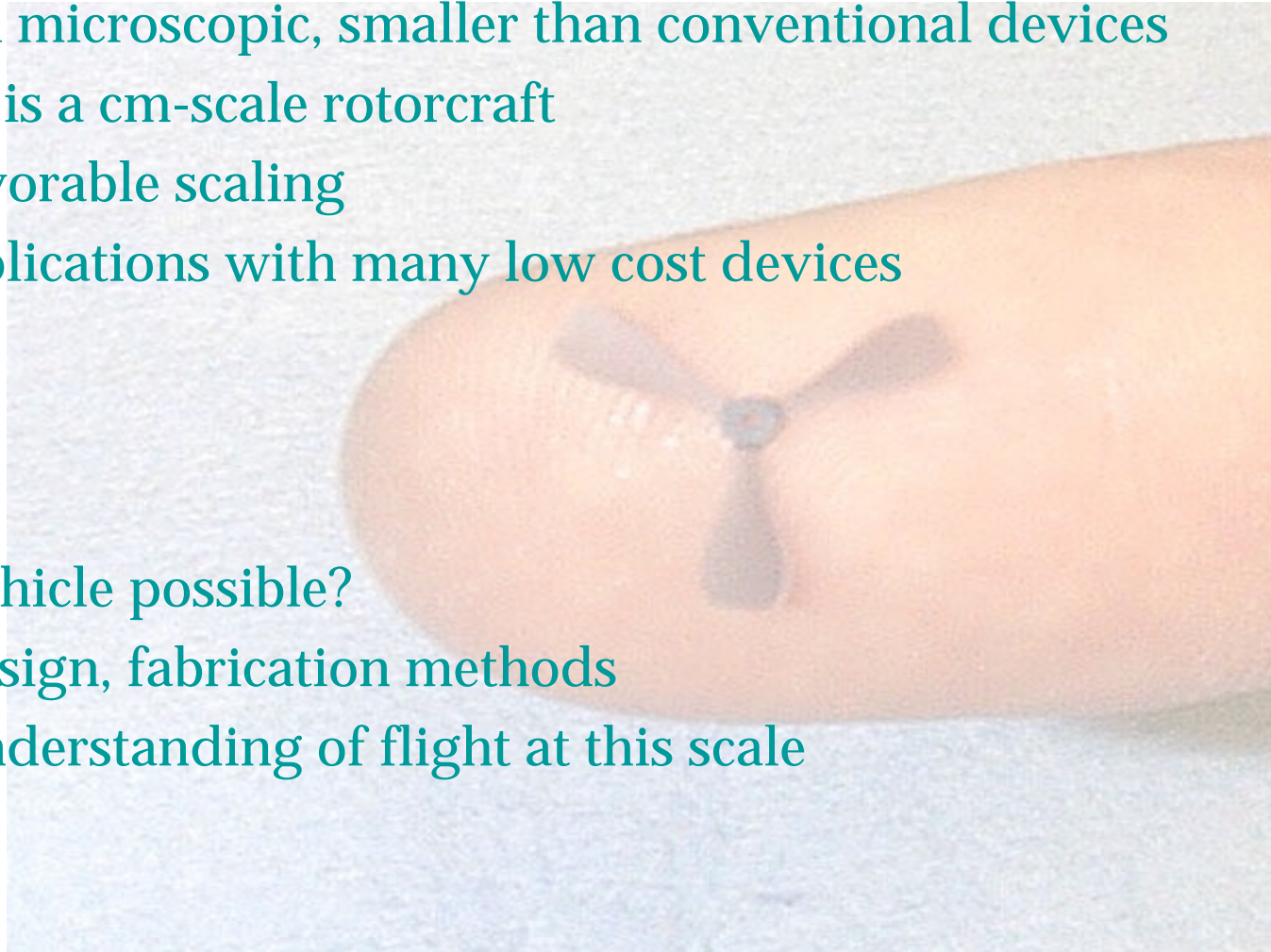
Graduate Students:

Sam Shomans, Rudolf Leitgeb, Shelly Cheng,
Peter Kunz, Scott Bowie, Mike Holden



The Concept: Meso-scale Flight

- What is a meso-scale vehicle?
 - ◆ Larger than microscopic, smaller than conventional devices
 - ◆ Mesicopter is a cm-scale rotorcraft
 - ◆ Exploits favorable scaling
 - ◆ Unique applications with many low cost devices
- Objectives
 - ◆ Is such a vehicle possible?
 - ◆ Develop design, fabrication methods
 - ◆ Improve understanding of flight at this scale



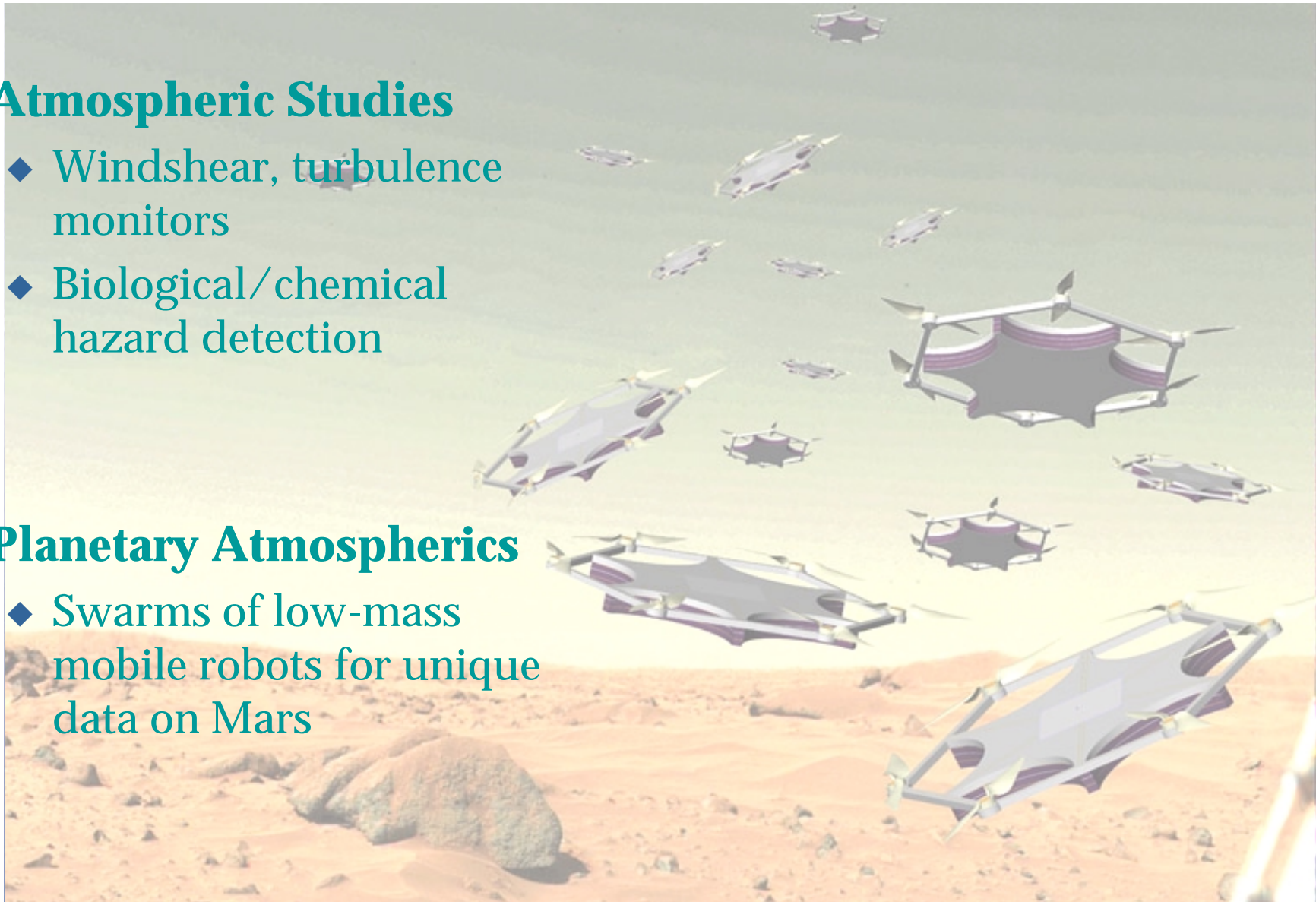
The Concept: Applications

■ Atmospheric Studies

- ◆ Windshear, turbulence monitors
- ◆ Biological/chemical hazard detection

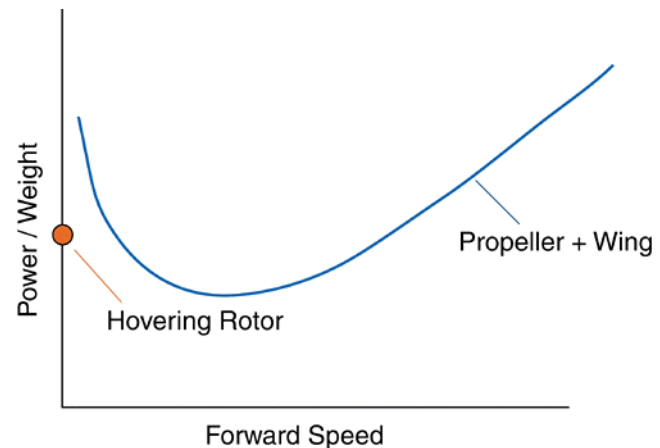
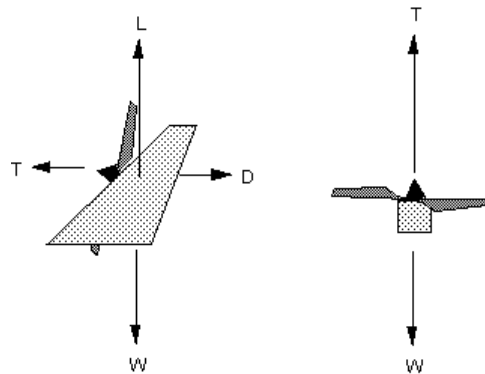
■ Planetary Atmospherics

- ◆ Swarms of low-mass mobile robots for unique data on Mars



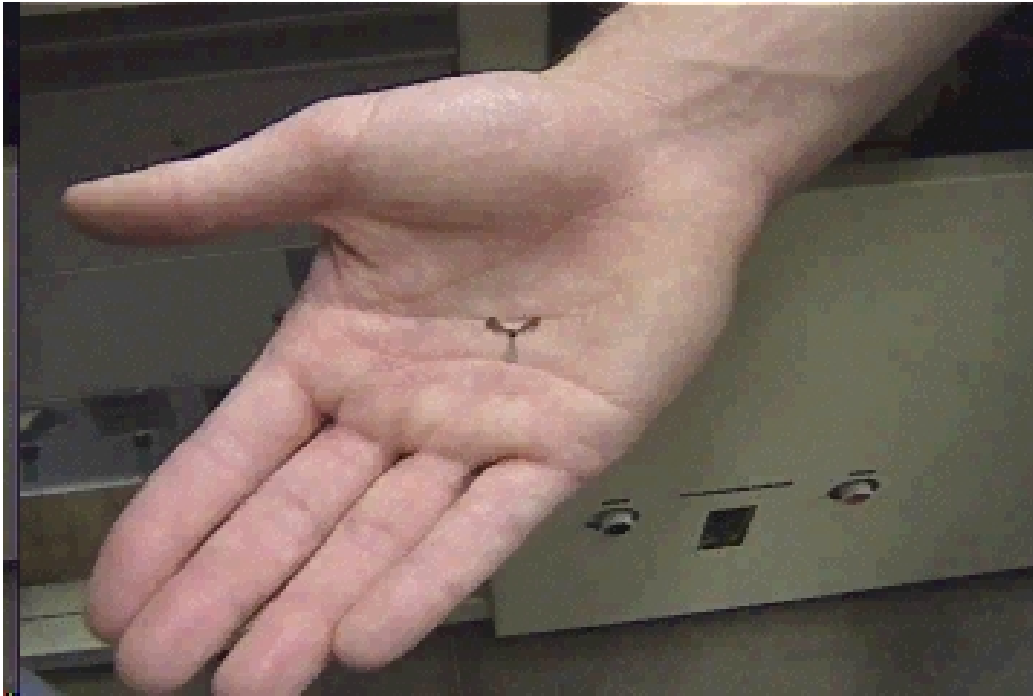
The Concept: Rotorcraft

- Why rotorcraft for meso-scale flight?
 - ◆ As Reynolds number and lift/drag decrease, direct lift becomes more efficient
 - ◆ Compact form factor, station-keeping options
 - ◆ Direct 4-axis control



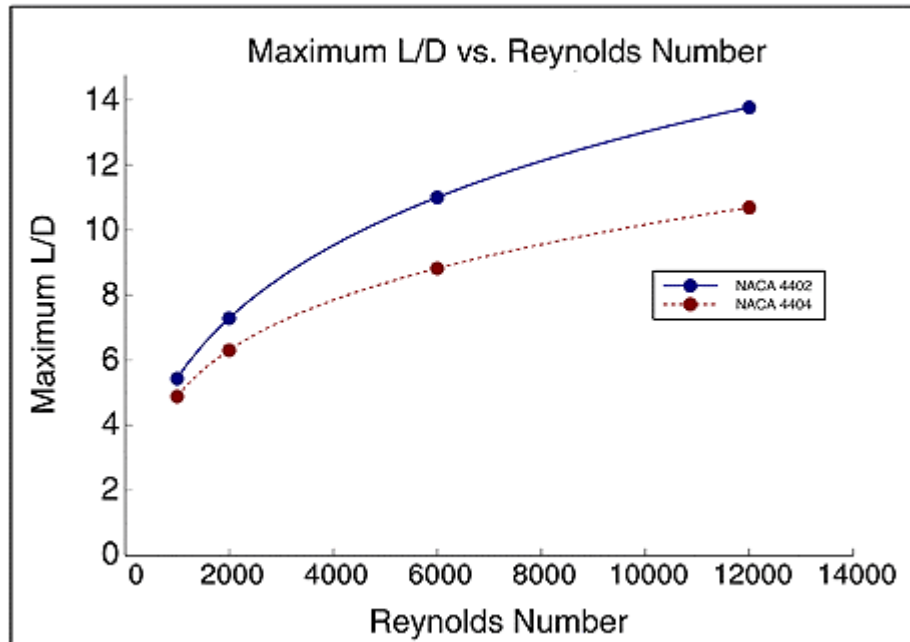
- Scaling laws (and nature) suggest cm-scale flying devices possible.

The Concept: Challenges



- Insect-Scale Aerodynamics
- 3D Micro-Manufacturing
- Power / Control / Sensors

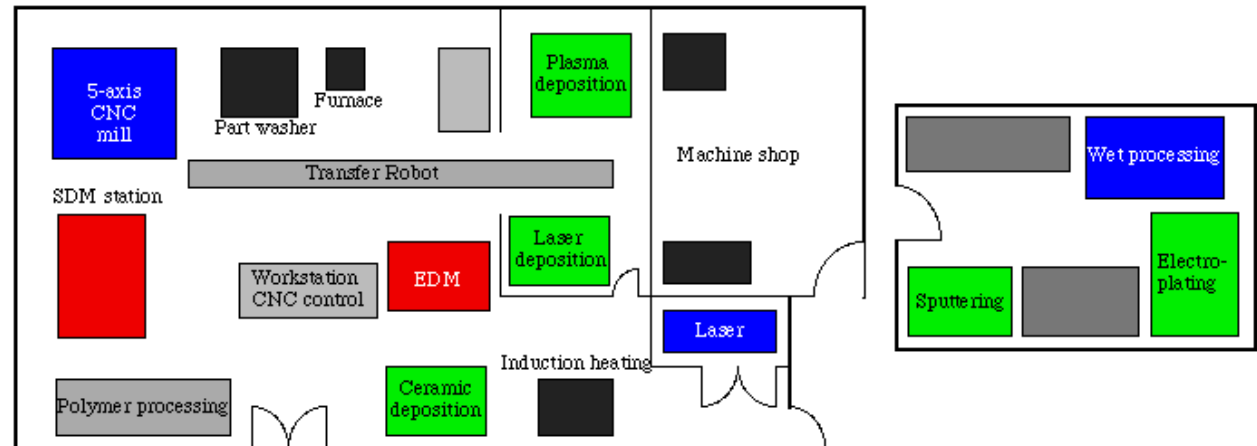
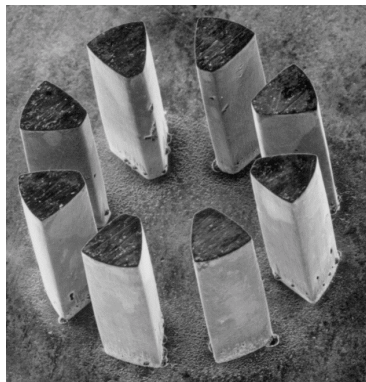
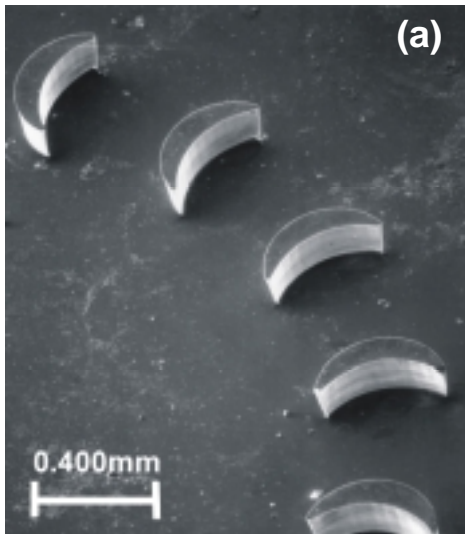
Challenges: Aerodynamics



- Insect-scale aerodynamics
 - ◆ Highly viscous flow
 - ◆ All-laminar
 - ◆ Low L/D
- New design tools required

Challenges: Micro-manufacturing

- Efficient aero requires 3-D rotor design with 50 μm cambered blades
- Micro-motor design, construction
- Integrated power, electronics



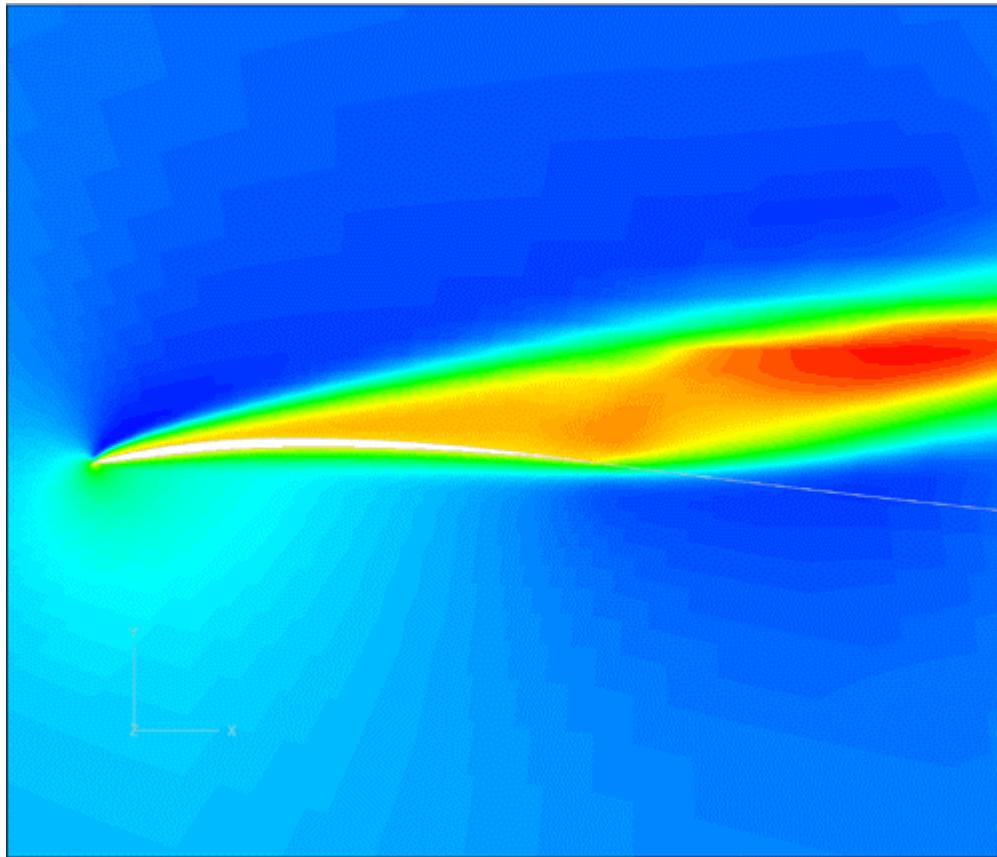
Equipment at Rapid Prototyping Lab

Approach

- Advanced aerodynamic analysis and design methods
- Novel manufacturing approaches
- Teaming with industry for power and control concepts
- Stepwise approach using functional scale model tests

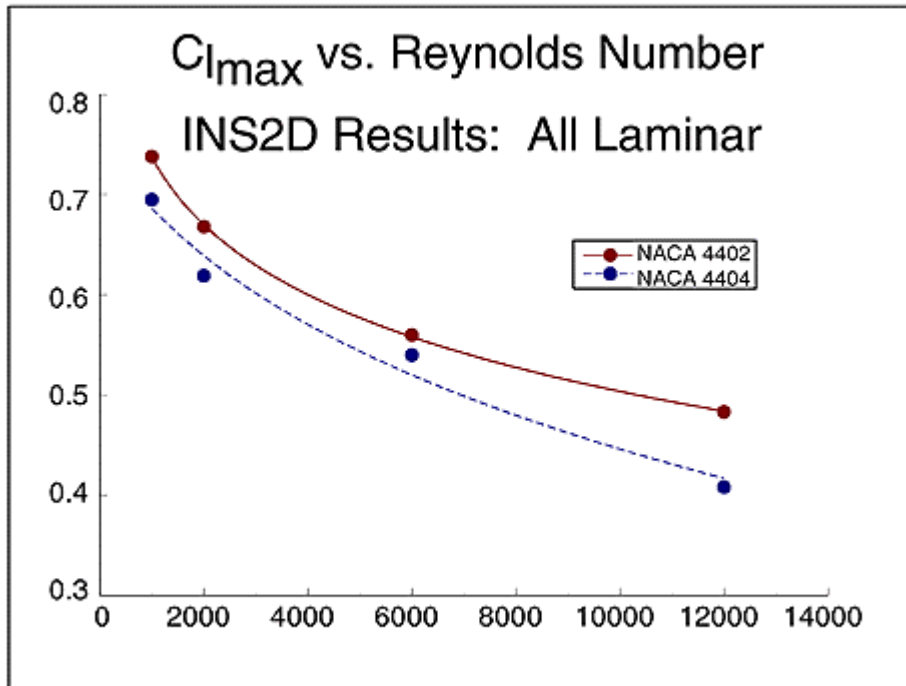


Approach: Aerodynamics



- Navier-Stokes analysis of rotor sections at unprecedented low Reynolds number
- Novel results of interest to Mars airplane program
- Nonlinear rotor analysis and optimization code

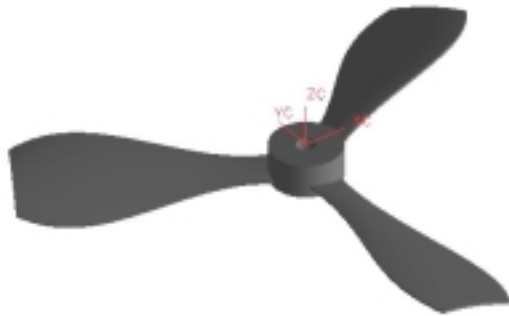
Approach: Aerodynamics



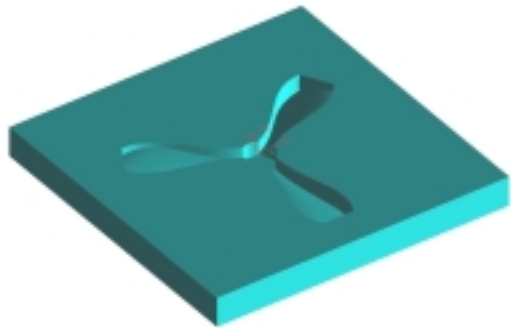
- New results for very low Re airfoils
- Very thin sections required
- Maximum lift increases as Re decreases below 10,000

Approach: Rotor Optimization

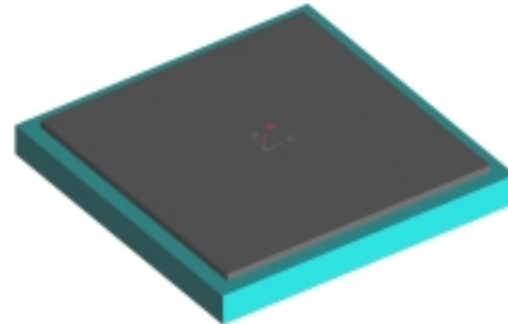
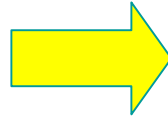
- Chord, twist, RPM, blade number designed using nonlinear optimization
- 3D analysis based on Navier-Stokes section data
- Rotor matched with measured motor performance



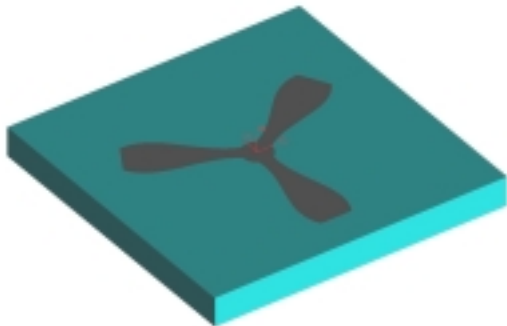
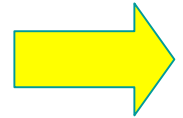
Approach: Rotor Manufacturing



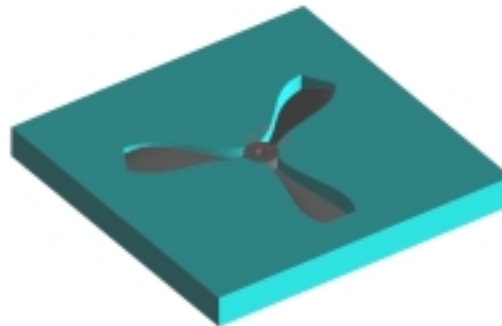
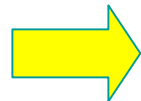
1. Micro-machine bottom surface of rotor on wax



2. Cast epoxy



3. Remove excess epoxy



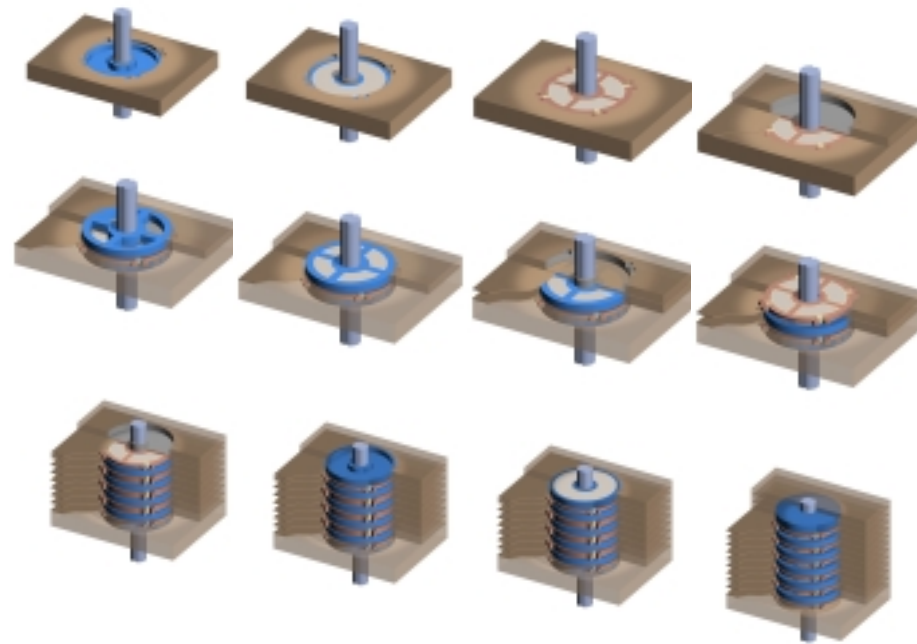
4. Machine top surface of rotor



5. Melt wax

Approach: Micro-Motor Development

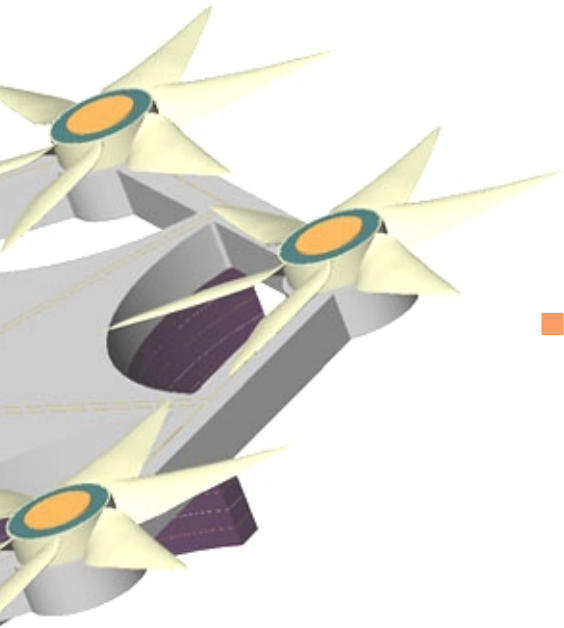
- 1mm diameter micro-motor constructed using SDM
- Fabrication complete, first spinning tests underway
- Initial rotor tests use 3mm brushless DC motor



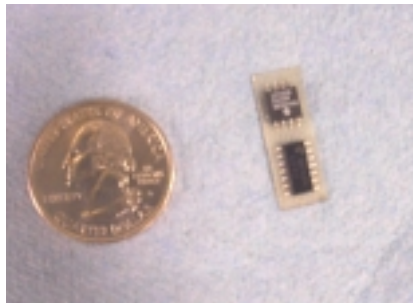
Steps in micro-motor fabrication

Approach: Battery Technology

- New lithion-ion technology provides 130 mW hr/g -- will power prototype mesicopter for 30 min of flight.
- SRI partners developing “direct-write” battery under DARPA program. High energy density system integrated with small-scale structure.

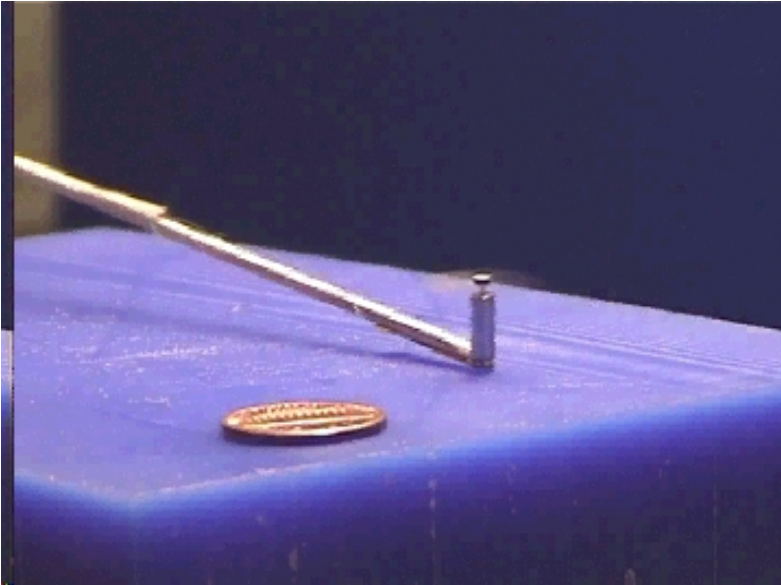


Approach: Sensors / Controls



- Innovative passive stabilization under test at larger scale
- Micro-motor controllers in development
- Inter-chip communication concept studied by industry partner

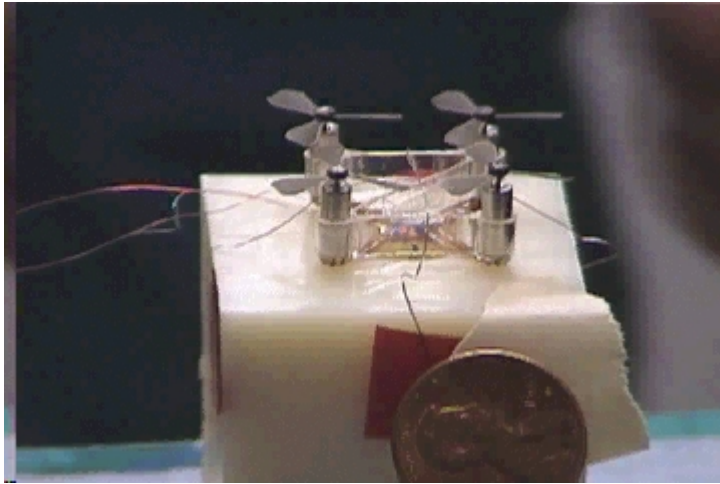
Status



- 1.5 cm rotors designed, tested
- 4-Rotor concept constructed, initial tests complete
- Single rotor performance characterized using 3mm, 325mg motor, external power

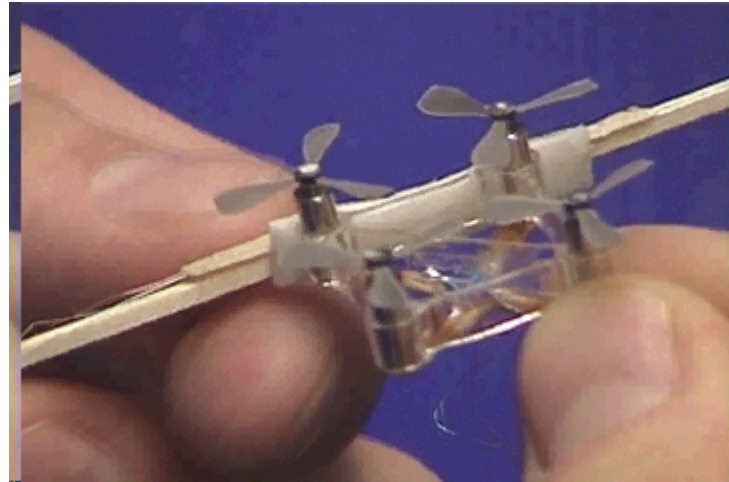


Status: Initial Prototypes



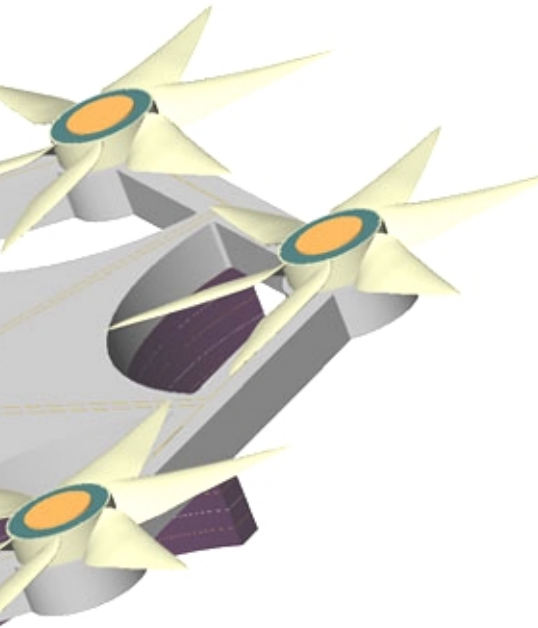
- 4-Rotor design fabricated, assembled 3/18/99
- Initial tests successful

Status: Initial Prototypes



- Initial tests stabilized on pivot arm
- Weight excludes power and controller
- Current estimates suggest 1.5cm mesicopter can lift batteries, controller as well

Current Work



- Rotor testing, optimization
- Micro-motor development
- Integration of power/motor controls
- Discussions with SRI, Intel, NASA on batteries, communications, sensor options

Continuing Work / Future Visions

- First flight of world's smallest free-flight powered aircraft imminent
- Program will lead to:
 - ◆ New manufacturing approaches and design tools for miniature devices
 - ◆ Fundamental understanding of small-scale flow for terrestrial or Mars aircraft
 - ◆ New generation of flight vehicles that act in concert to provide an unprecedented sensor platform

