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# ***An Architecture of Modular Spacecraft with Integrated Structural Electrodynamic Propulsion (ISEP)***

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*Engineering the Future*

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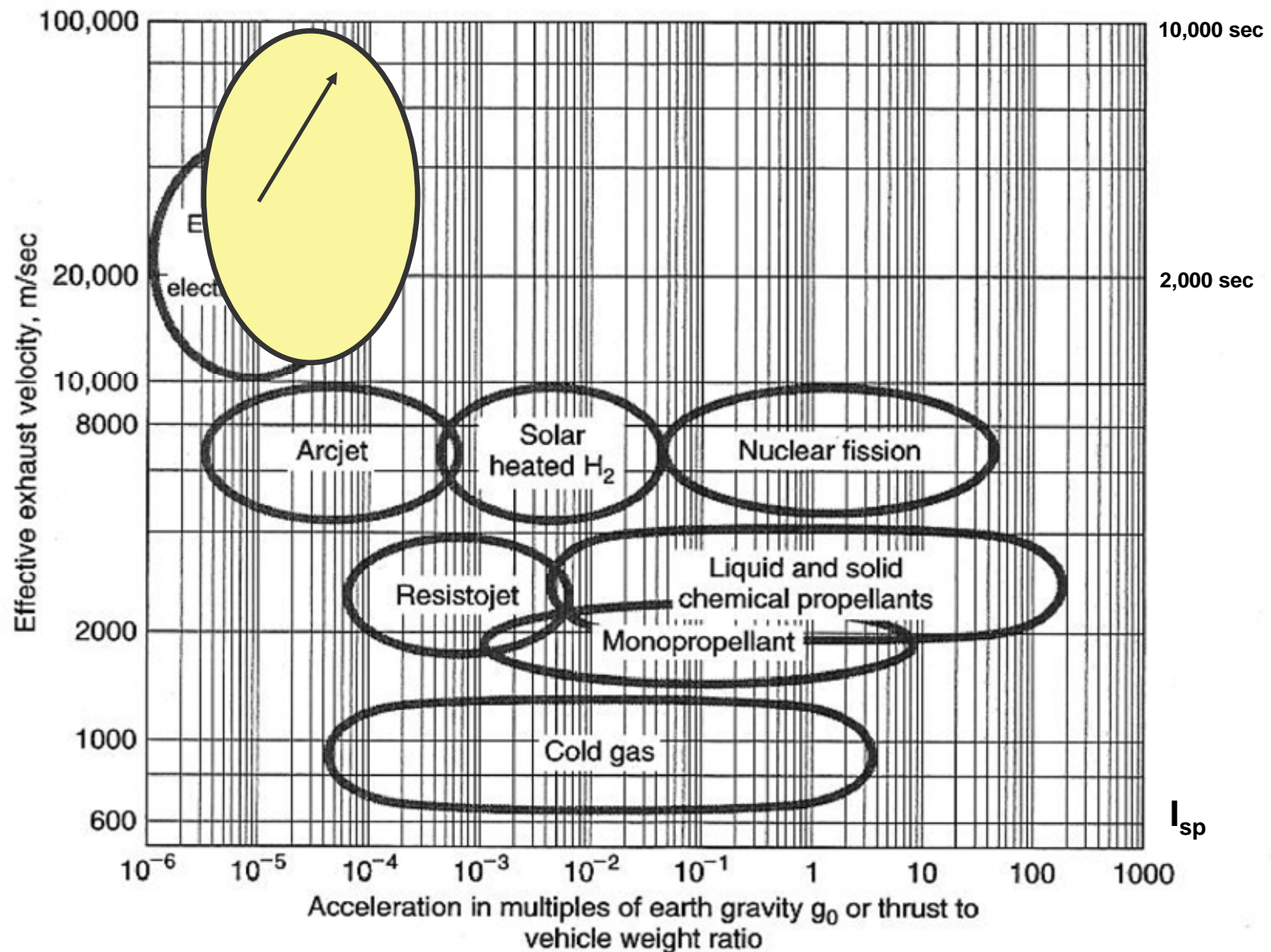
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# Motivation

- Traditional propulsion uses propellant as reaction mass
- Advantages (of reaction mass propulsion)
  - Can move spacecraft center of mass, on-demand, and relatively quickly
  - Multiple thrusters offer independent and complete control of spacecraft (6DOF)
- Disadvantages
  - Propellant is a finite and mission limiting resource
  - Propellant mass requirements increases exponentially with mission  $\Delta V$  requirements
  - Propellant may be a source of contamination for optics and solar panels
- Current Architectures of NASA's Vision of Exploration require launching and transporting large masses
- Are there innovative alternatives?

# Space Propulsion Landscape



# Electrodynamic Space Tether Propulsion

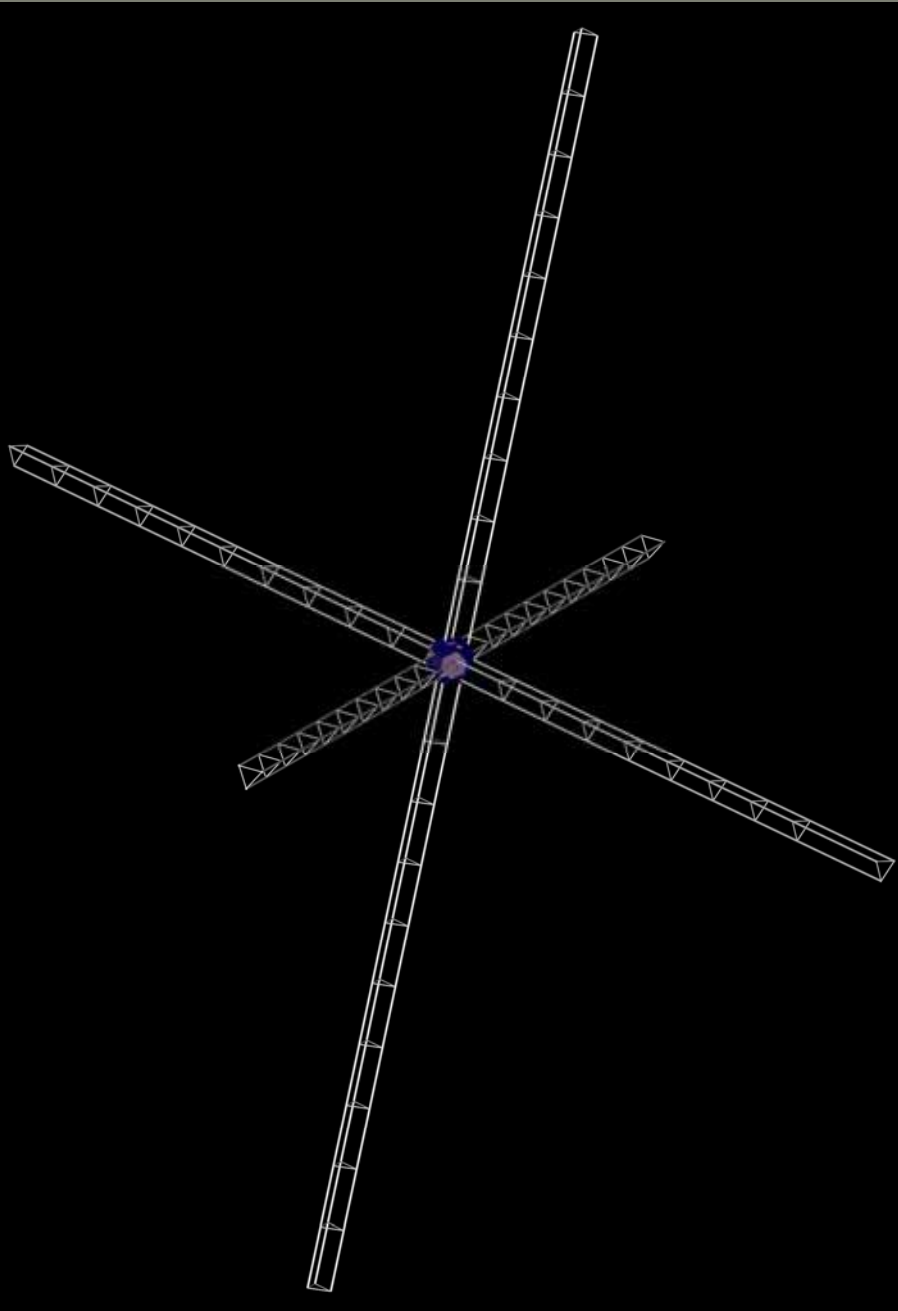
- In-space propulsion system
- PROS:
  - Converts electrical energy into thrust/orbital energy
  - Little or no consumables are required
- CONS:
  - Long (1-100km) flexible structures exhibit complex dynamics, especially in higher current/thrust cases
  - Gravity gradient tethers have constrained thrust vector
  - Relies on ambient plasma to close current loop



Given a fixed amount of power available and fixed conductor mass, thrust efficiency is independent of the length of the conductor



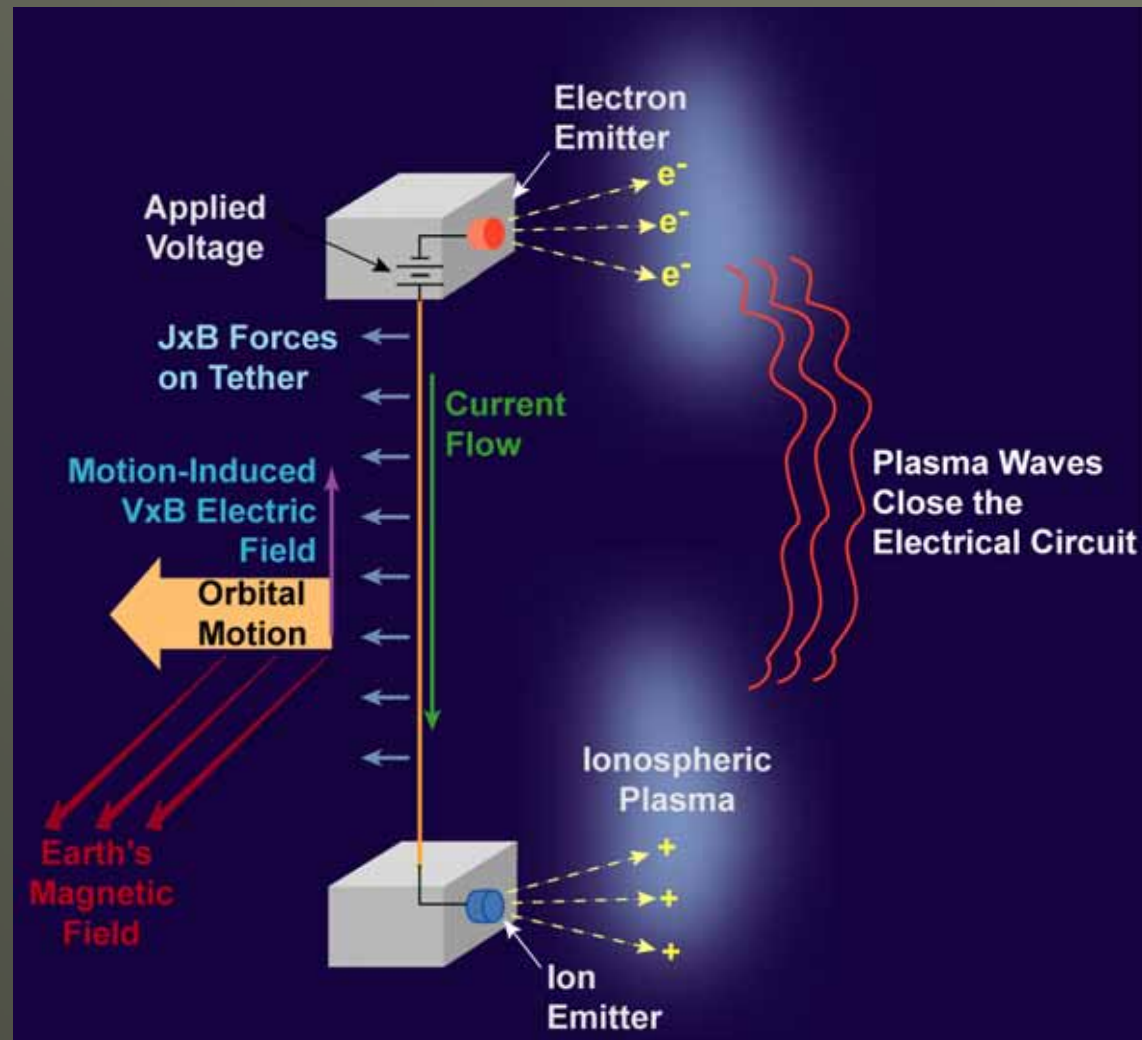
# Proposed Solution



- *Multifunctional* propulsion-and-structure system that utilizes Lorentz forces ( $F = iL \times B$ ) generated by current carrying booms to generate thrust with little or no propellant expenditure
  - Utilizes same principles as electrodynamic tether propulsion
- Utilize relatively short ( $\approx 100$  meter), rigid booms with integrated conductors capable of carrying large currents, that have plasma contactors at the ends
  - Space Tether Electrodynamic Propulsion
    - Ex: 10km conductor, 1Ampere in LEO
      - Thrust  $|iL \times B| \approx 0.3$  Newtons
- Proposed Integrated Structural Propulsion
  - Ex: 100m conductor, 100 Ampere (!) in LEO
    - Thrust  $|iL \times B| \approx 0.3$  Newtons
    - Torque  $\approx 750 \text{ N} \cdot \text{m}$

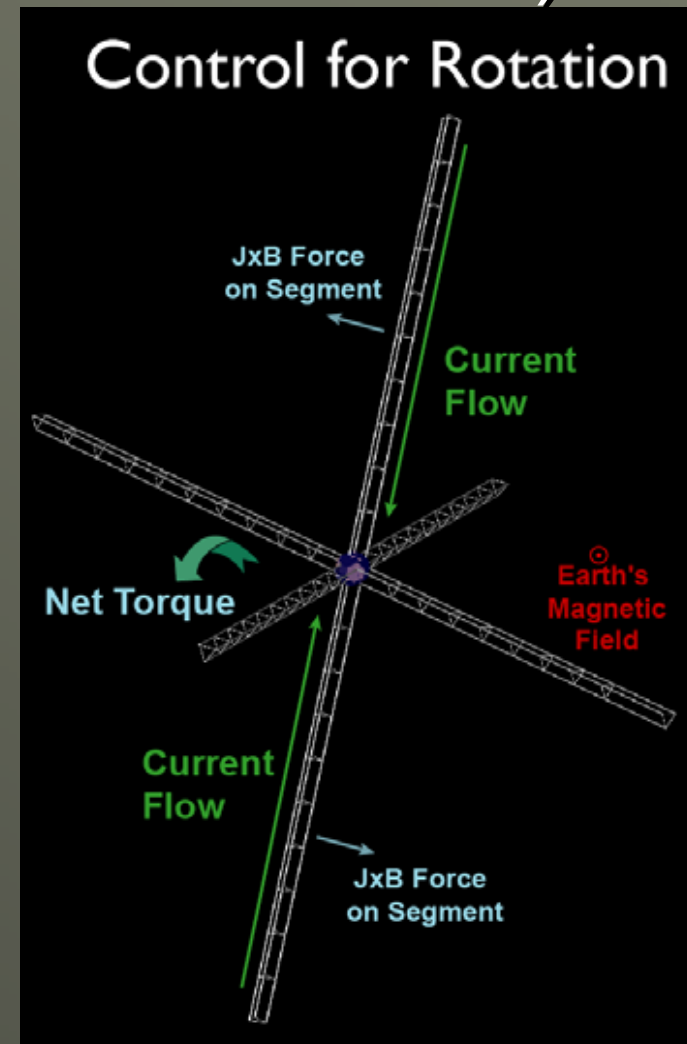
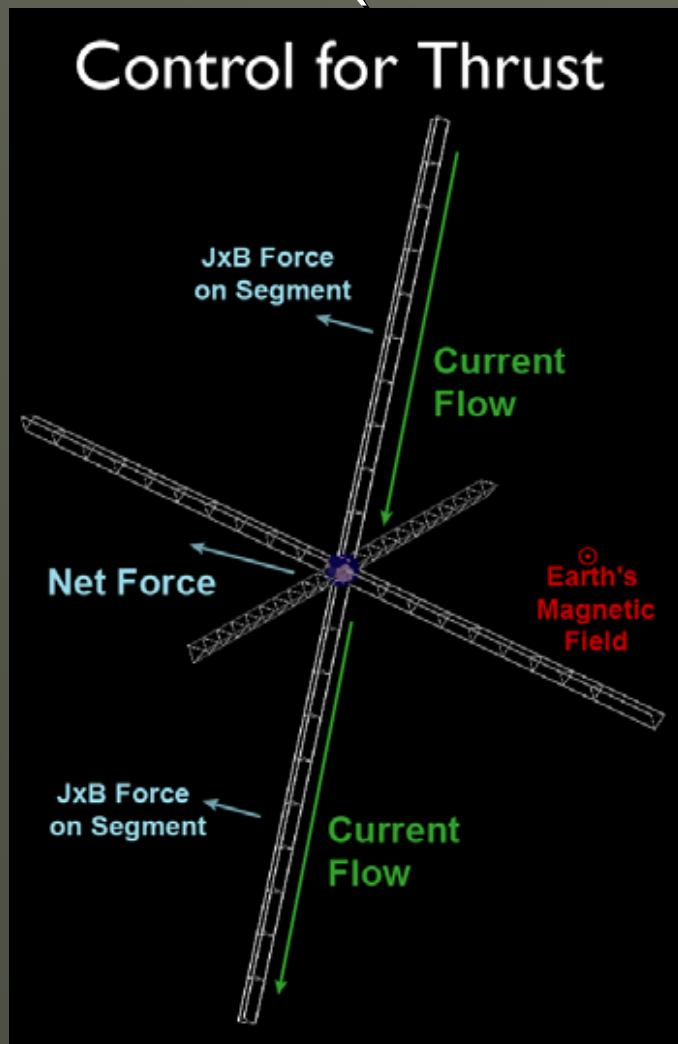
# Single Boom Concept of Operation

- Apply potential to overcome motion-induced electric field and drive current across magnetic field
- Current flowing down boom produces thrust force
- Plasma waves close the electrical circuit



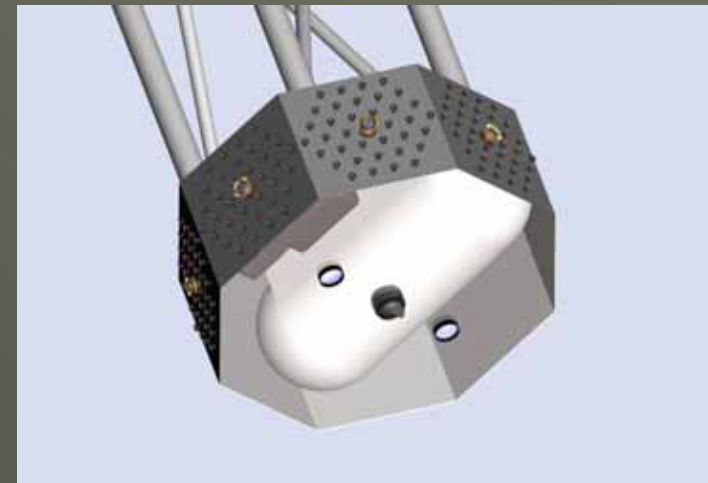
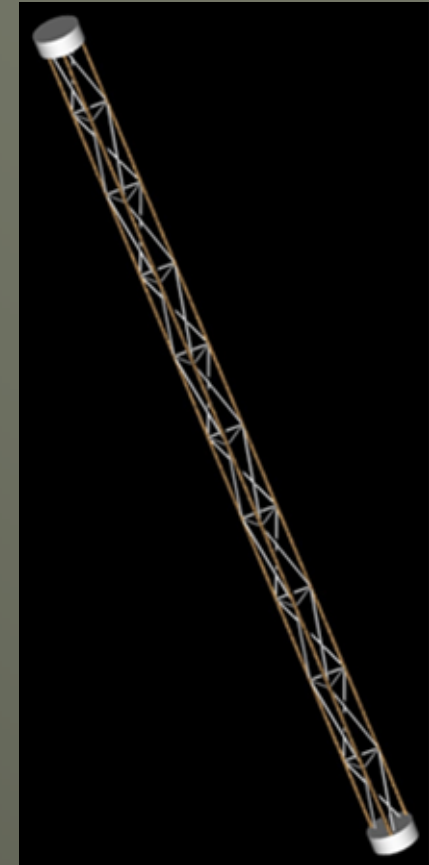
# 'Structural' ED Propulsion

- By connecting six booms to a spacecraft along orthogonal axes, 4DOF of motion can be controlled (translational and rotational)



# ISEP Booms

- Cold biased, low-resistance element to maximize propulsive performance
  - Copper Clad Aluminum (CCA) offers low specific resistivity, yes remains easy to work with
    - Ex.  $0.01\Omega/50$  meter boom has a  $0.44$  kg/m density
- Stiffness dictated by application
- Boom ends contain plasma contactors & docking sensors
- Hemaphroditic high-current capacity docking mechanism





# 100 Ampere Contactors for ISEP

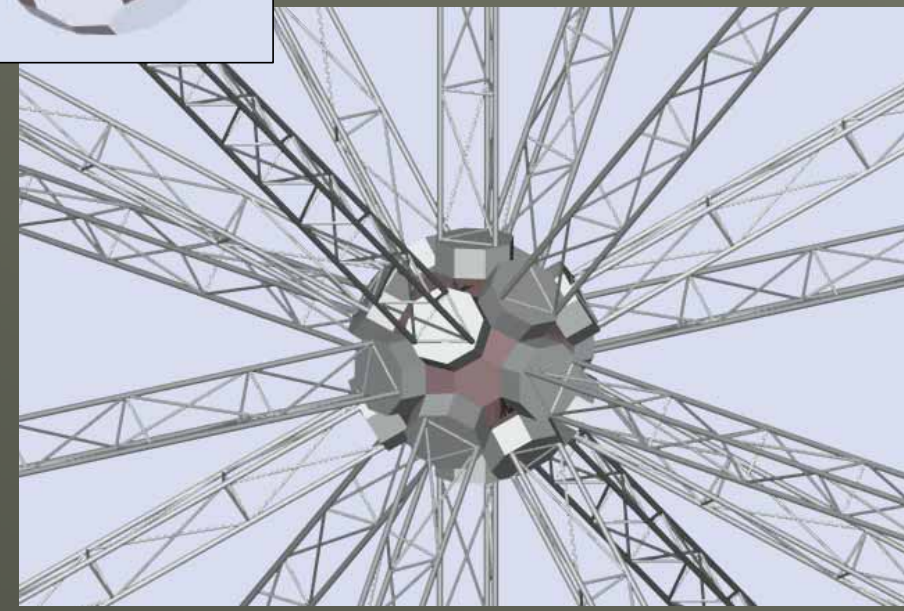
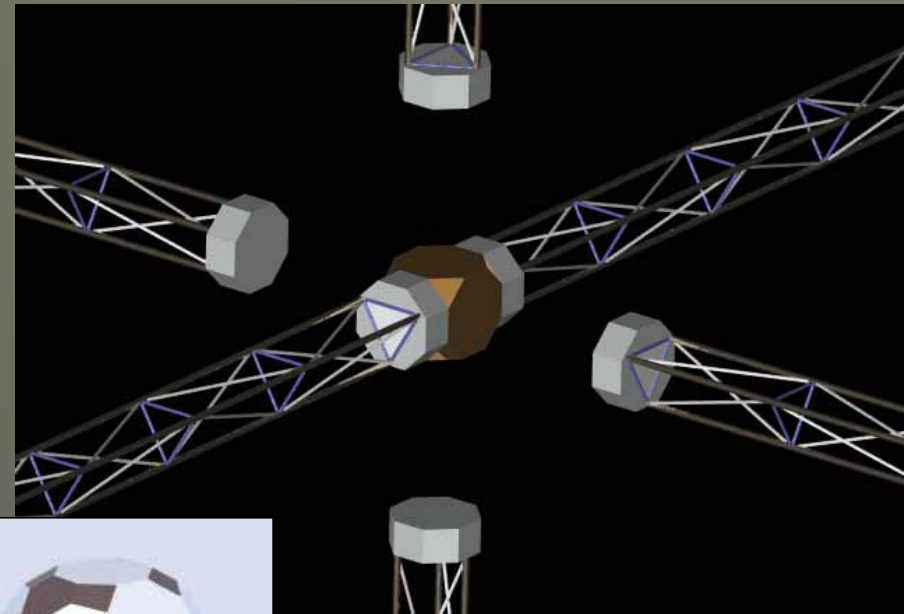
Emission	Device	Power	Notes
Electron Emission	TC + Electron Gun	2.1 MW	18 emitters, < 1.25 V for SCL
	<b>FEA</b>	<b>5860 W</b>	<b>10 emitters, &lt; 0.4 V for SCL</b>
	<b>HC</b>	<b>1250 W to 10 kW</b>	<b>Flow Rates &amp; Ion Type</b> <b>9 sccm to 40 sccm Xe</b>
Electron Collection	Passive Sphere a	4.7 MW	1 m radius, 6.6E-3 N Drag 90% Porous – 6.6E-4 N
	Passive Sphere b	1 MW	2.29 m radius, 3.46E-2 N Drag 90% Porous – 3.46E-3 N
	Passive Plate a	61.3 MW	5 m <sup>2</sup> – 5.26E-5 N Drag
	Passive Plate b	1 MW	54.52 m <sup>2</sup> – 5.73E-4 N Drag
	HC	6150 W + 330 W (20 A ion prod.)	280 sccm fuel 27.35 mg/s Xe <sup>+</sup> or 0.21 mg/s H <sup>+</sup>
Ion Emission	Ion Emission + Ion Gun	1 MW + 1650 W (100 A ion prod.)	83,334 emitters needed
	<b>HC</b>	<b>1000 W + 1650 W</b> <b>(100 A ion prod.)</b>	<b>1400 sccm fuel</b> <b>27.35 mg/s Xe<sup>+</sup> or 0.21mg/s H<sup>+</sup></b>

# ISEP Nodes

- Node geometry
  - Simplest has 6 orthogonal mating surfaces
  - Can also utilize polyhedrons with mating surfaces spaced  $45^\circ$  along the circumference

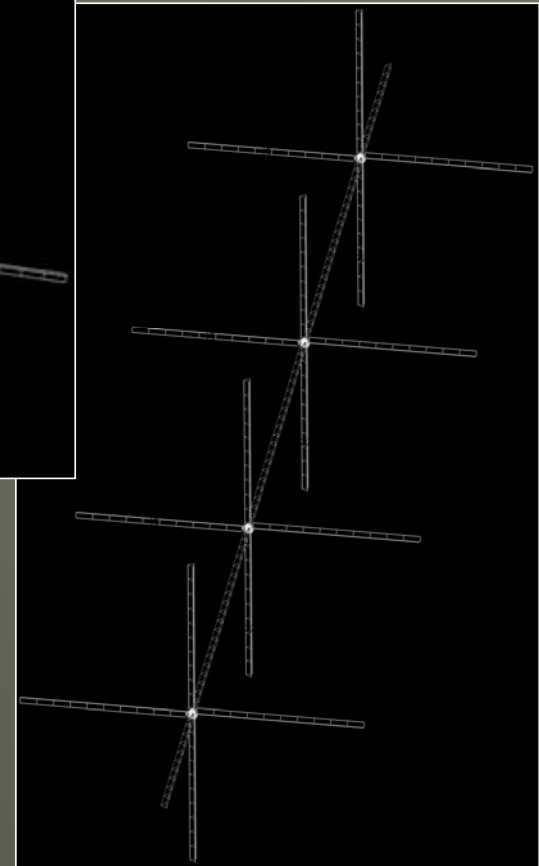
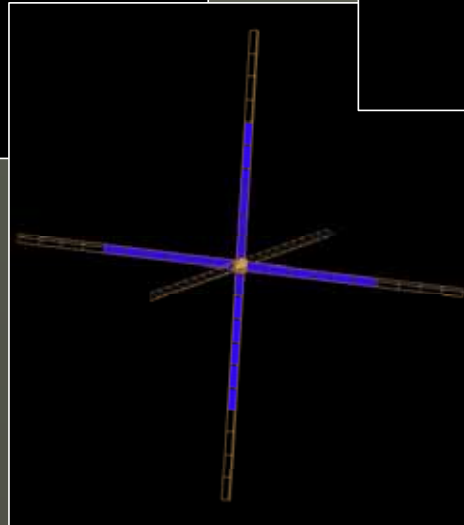
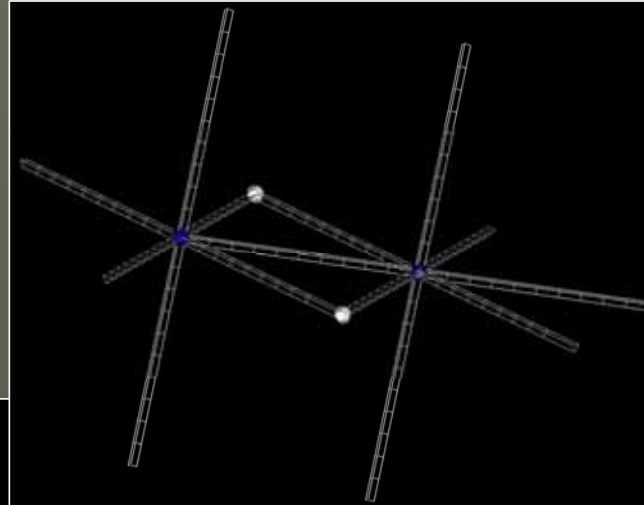
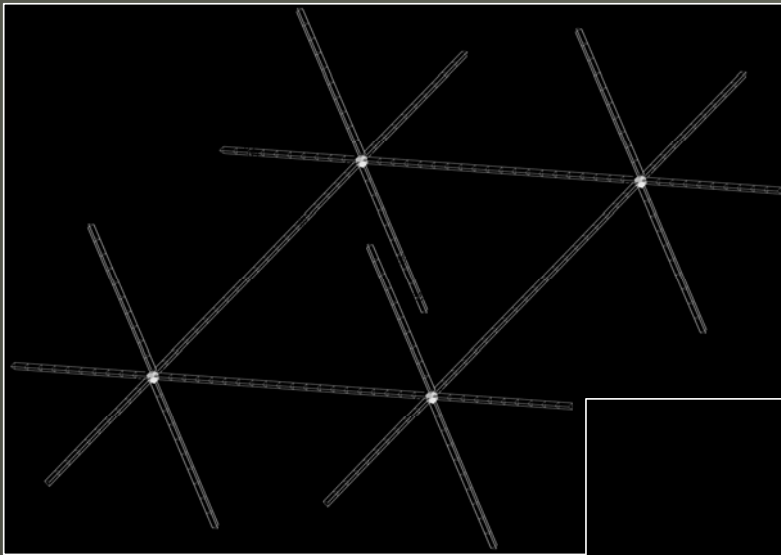
- Node components

- Energy storage (flywheels @ 75 W-hr/kg)
- System & Navigation Controllers



# Modular Spacecraft

- By making booms and spacecraft modules modular and interconnectable, we create self-assembling Tinkertoy<sup>®</sup> like components for space structures and systems



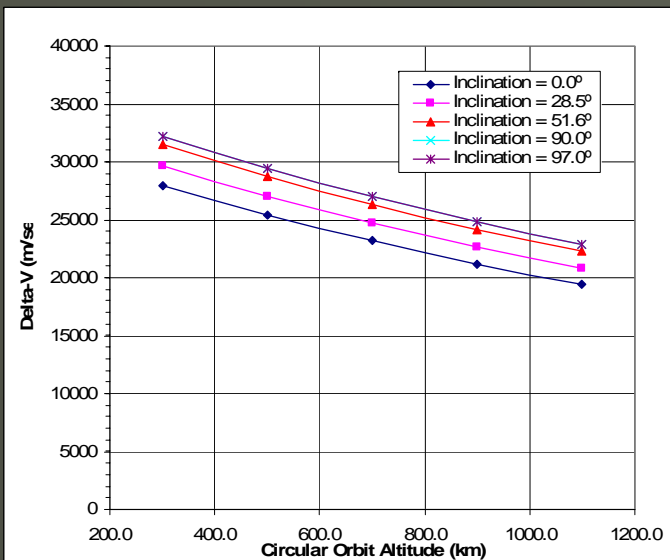
# ISEP Applications

- Self-Assembling Modular Spacecraft (SAMS)
- Self-Assembling Structure for Refueling Station
  - Integral rail gun for commodity delivery
- Self-Assembling Space Tug
- Self-Assembling Structure for Large Mirror or Antenna Arrays
- Formation Flying Space Systems
  - Terrestrial Planet Finder (TPF)

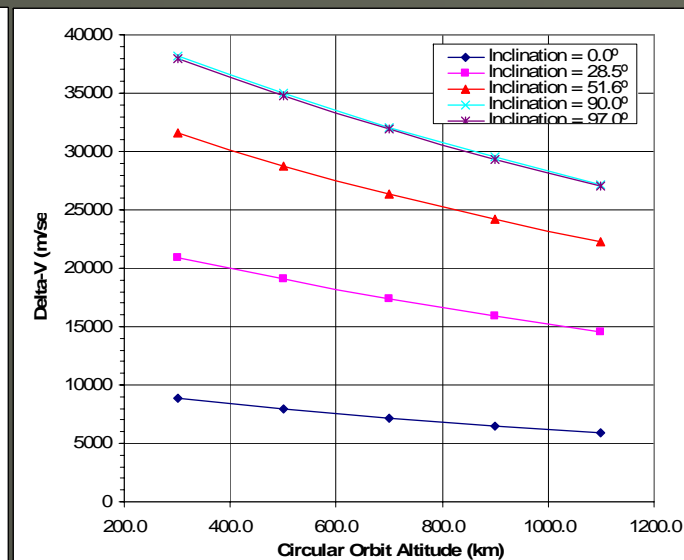


# ISEP Performance Analysis

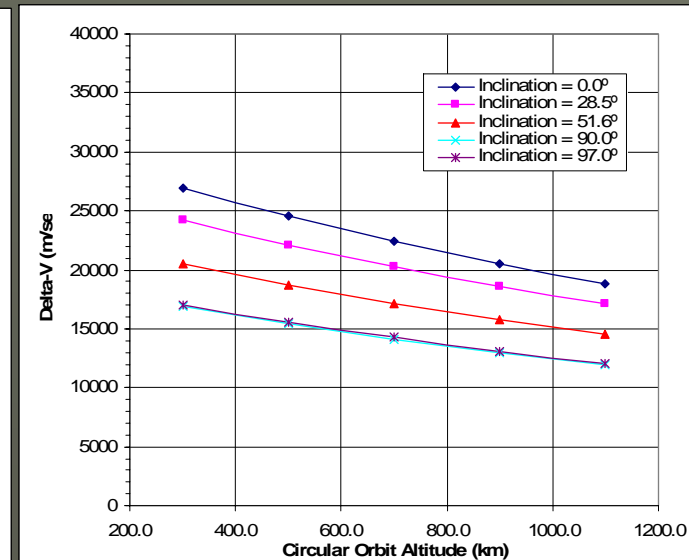
- Six 50m orthogonal booms in 300-1100km, 0-97° inclination orbits
- FEAs for electron emission, HCs for ion emission
- Total system mass – 1000kg with 20kg H consumable (approx 3 years full time operation)
- Current commanded to 100A continuous for 30 days
  - System Input power - 6500 Watts
- Performance metrics tabulated & averaged



Along-track Total  $\Delta V$



Cross-track Total  $\Delta V$

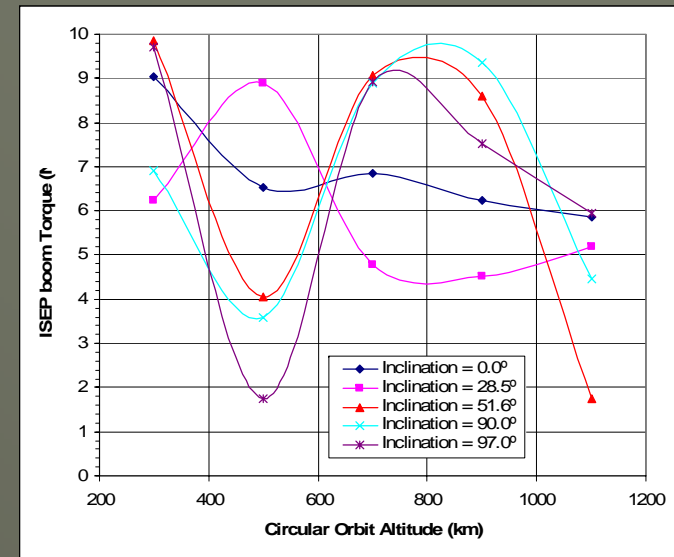


Radial Total  $\Delta V$

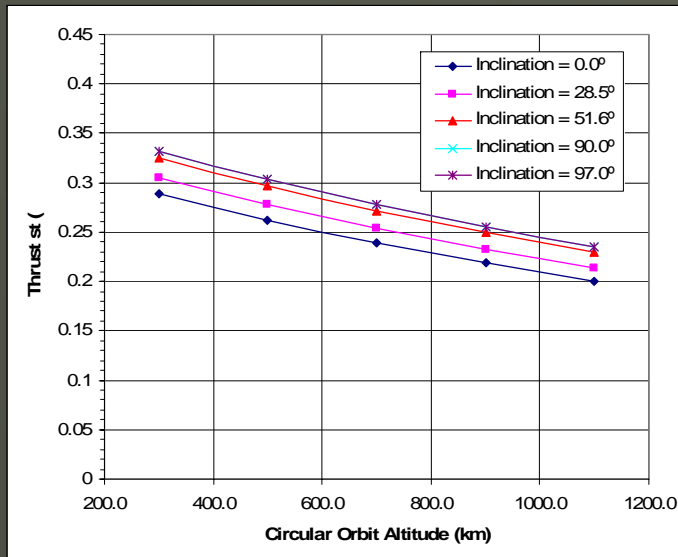


# ISEP Performance (cont.)

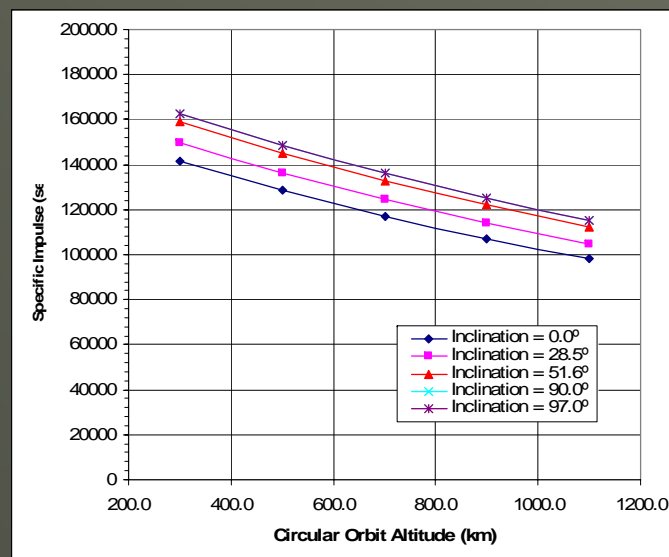
- Thrust magnitude and efficiency highly dependent on alignment of boom(s) with magnetic field
- Torques in the 1-10 N-m range as compared to disturbances in the  $10^{-8}$  to  $10^{-1}$  range



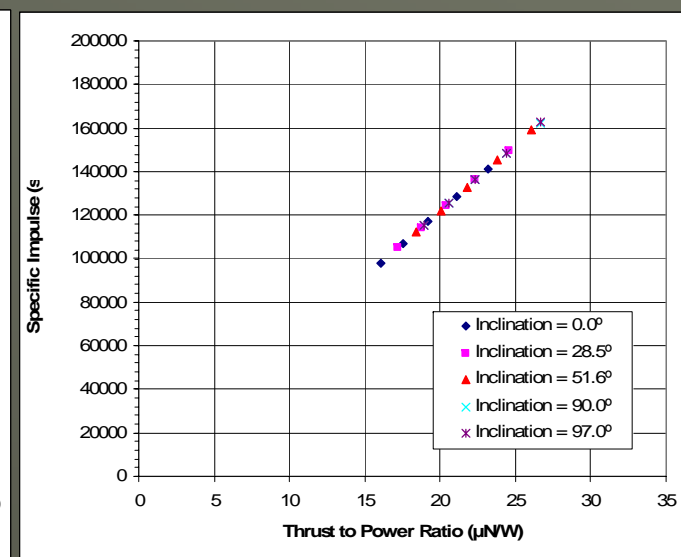
Along-track current torque (N-m)



Average Along-track Thrust (N)



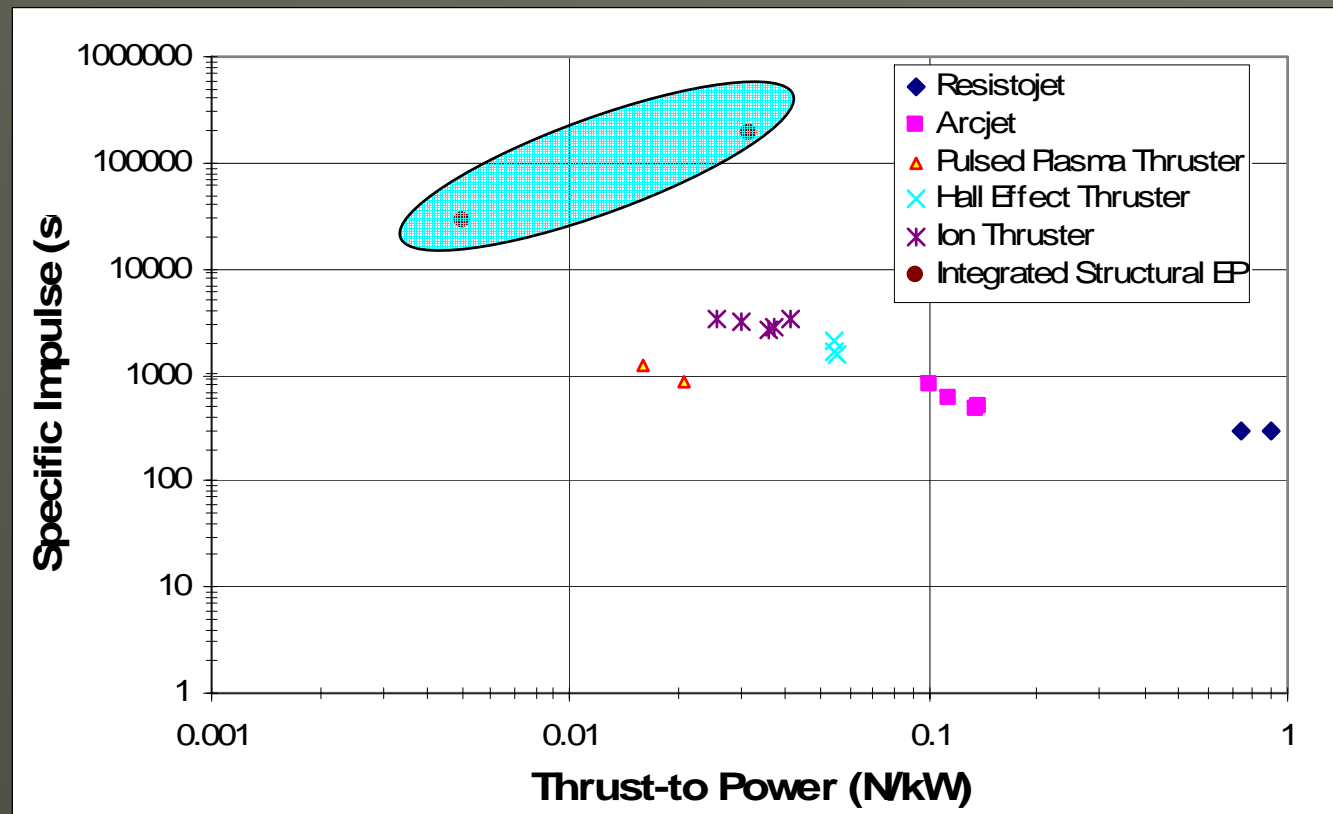
Average Specific Impulse (Isp)



Isp vs. Thrust to Power (μN/w)

# ISEP Performance

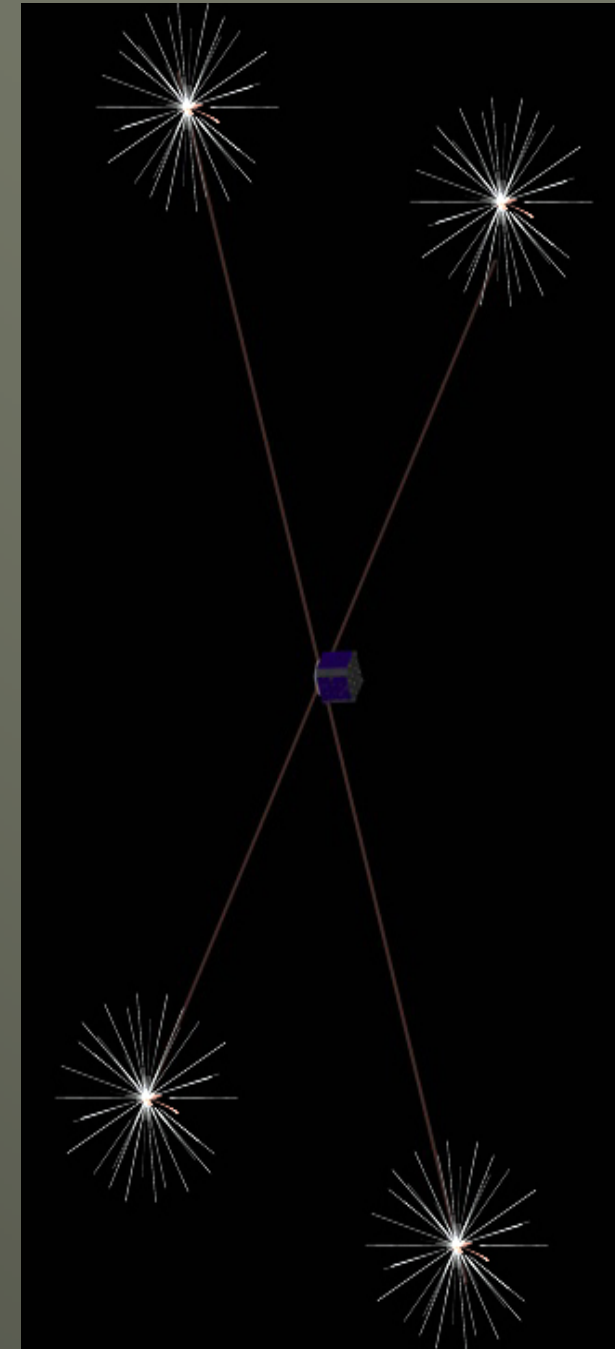
- ISEP is competitive with other EP technologies
- In systems where collinear booms are assembled, performance improves
- For missions where structural elements are required, ISEP's dual use (propulsive/structural) has significant advantages



- KEY TECHNOLOGY CHALLENGE: Power- and Mass- Efficient collection and emission of electrons from/to the ambient plasma

# Technology Demonstration Experiment

- Primary Experiment Objectives
  - Generate directly detectable torque
  - Generate directly measurable thrust
- Secondary Experiment Objectives
  - Validate performance of Field Emissive Electron device(s)
  - Validate performance of lightweight electron collectors
- **GOAL:** Drive 1 Ampere of current through lightweight deployable, conductive 10-20 meter booms
  - 0.2-1.0 second impulses  $> 0.5$  mN



# Experimental Method

- Picosatellite launched as a secondary payload
- Target platform – CubeSat
  - 1kg – 10x10x10 cm envelope
  - Standard initially designed for University class experiments and educational purposes
  - Typically 1-2 launch opportunities a year
  - Launch costs \$40-120K for a 1U CubeSat
  - Ideal for simple experiments and technology demonstrations



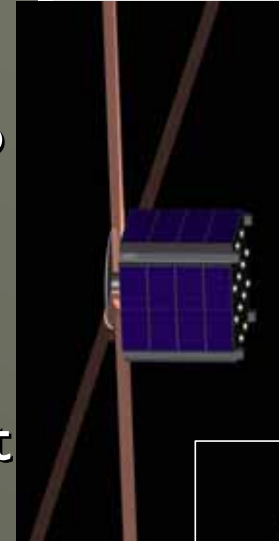
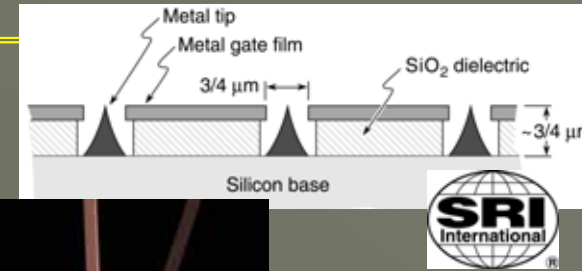
Poly Picosatellite Orbital Deployer (P-POD)



# Picosat Experiment Contactors

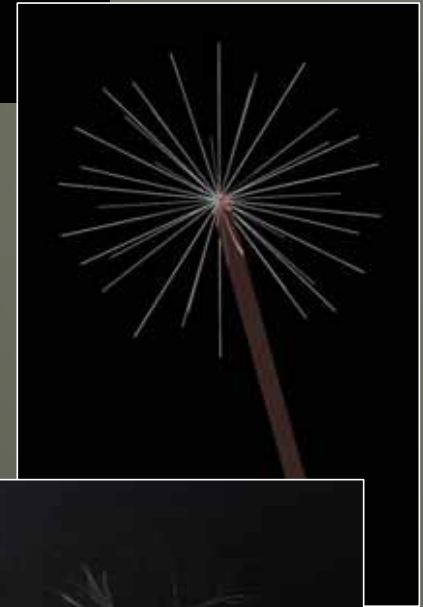
## Field Emissive Cathodes

- Microfabricated Emitter tips rely on sharp emitter tips, and close non-intercepting electrodes to generate high field required to enable electrons to quantum tunnel out of the material into space
- High current densities ( $5000\text{A}/\text{cm}^2$ ) have been demonstrated
- Development undergoing to increase total current output and reduce environmental constraints



## Passive Electron Collector ('Hedgehog')

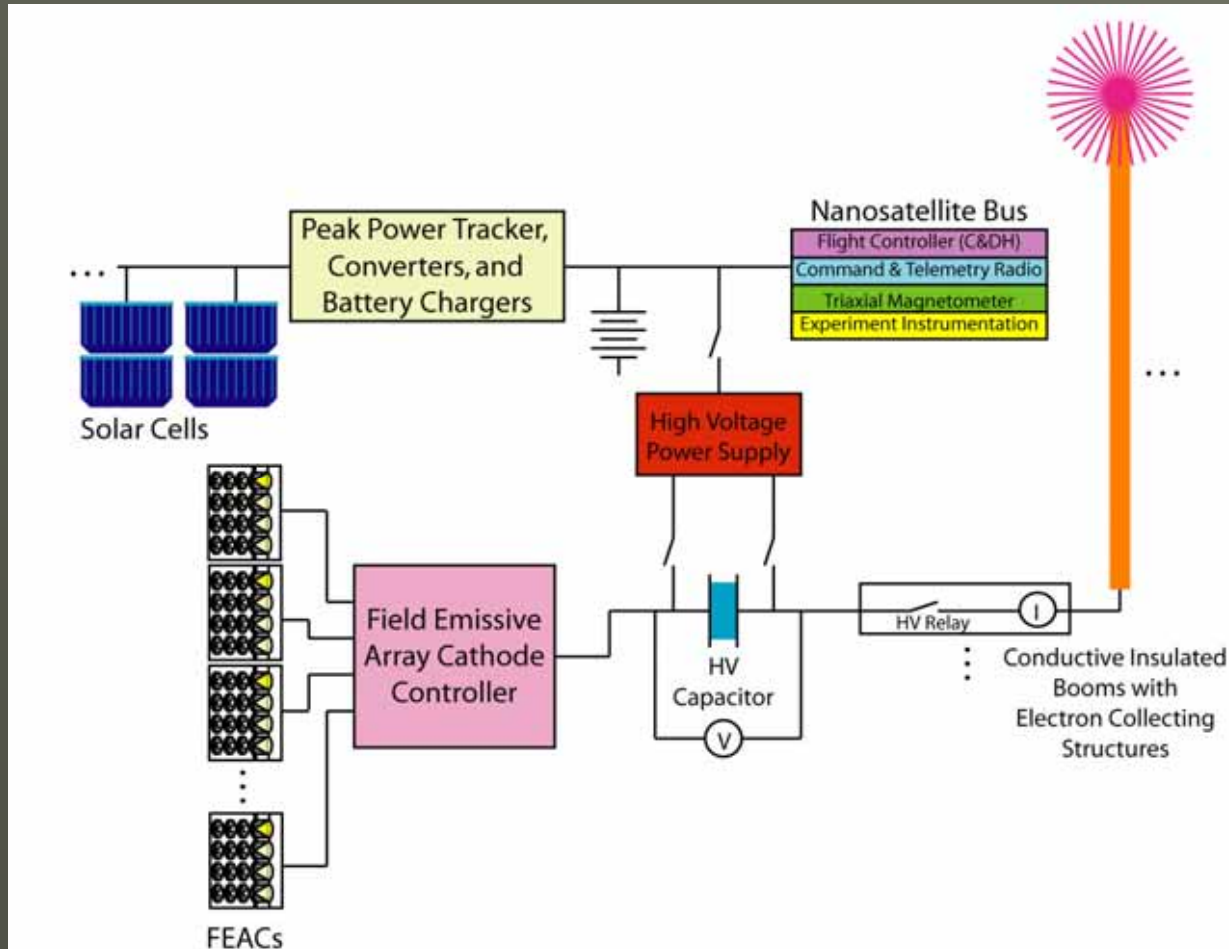
- Bundle of conductive yarns
- Yarns tied together at root, and when charged will form approximately a 'Koosh-ball' like spherical structure due to electrostatic repulsive forces
- 2 meter diameter structure with yarns every 40°, and filament every 1° can weigh 10 grams(!)





# Experiment Conops

- Converted Solar Energy is stored onboard in capacitor bank
  - Allow for thrust pulse every 4-6 orbits
- At desired B-field alignment, discharge capacitor to generate 1 Ampere pulse
- Measure Thrust with onboard accelerometers
- Measure Torque with body attitude rate change



# Summary

- Proposed Concept IS feasible
  - Requires small amount of consumables for ion source
  - 4DOF propulsion— no thrust in B-field direction
  - Competitive with tradition Electric Propulsion with added benefit of structural elements
- Technology Challenges
  - High Current Plasma Contactors
    - Devices exist – robust units with higher efficiencies needed
  - Plasma Contactor Space Charge Limiting
    - High current densities may be environmentally limited
  - Collision proof coordinated control laws for formation flight, and self-assembly
    - Additional constraints imposed on low-thrust control laws
- Experiment in Phase II will demonstrate system feasibility and validate component technologies
- Potential Applications
  - Space Tug and Commodity Depot (with integral rail gun?)
  - Structure for Beamed Power Solar Array/Antenna Fields
  - Structure for Space Habitats with Integral Drag Makeup