

Control of Spacecraft Swarms Using Coulomb Forces

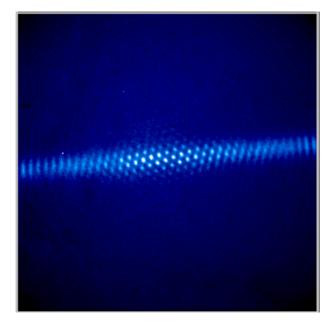
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This research made possible through funding from the NASA Institute for Advanced Concepts



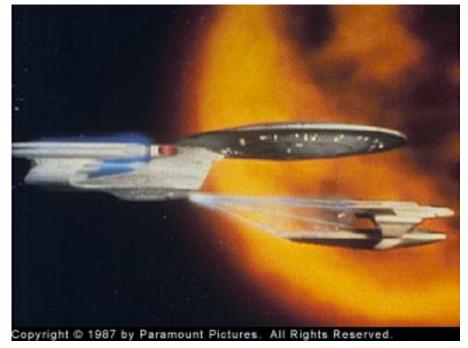
Motivation: Coulomb Clusters

Laser-cooled trapped ion research at NIST



- Ions in 1/r² confining potential form stable crystal formations
- What would charged spacecraft do in a gravity potential?

"How to build a tractor beam Without gravitons"





Presentation Overview

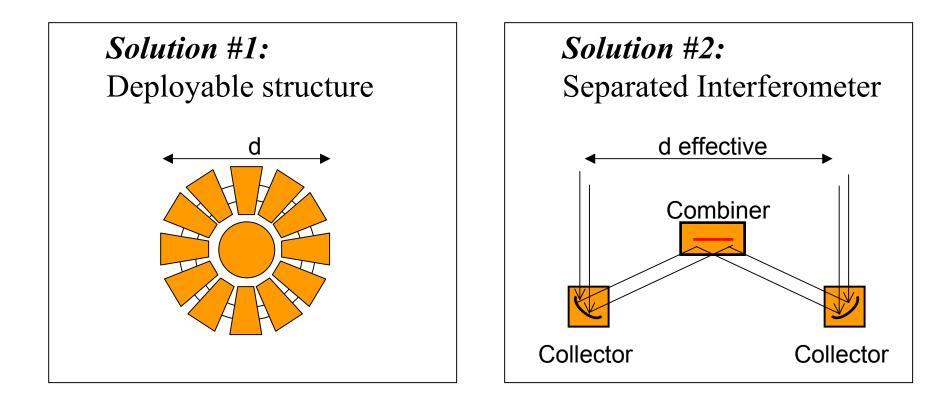
- Introduction to formation flying
- Space-based imaging and interferometry
- Formation propulsion requirements
- Spacecraft charging as control force
- Coulomb force metrics
- Coulomb formation orbital dynamics



Space-based Imaging Concepts

Space-based imaging problem:

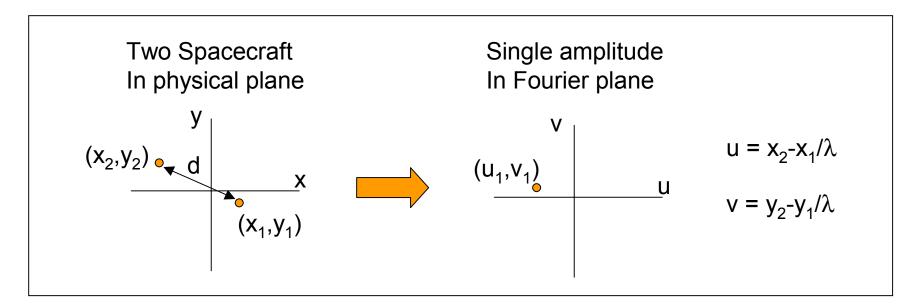
- Image resolution limited by size of aperture: $\theta = \lambda/d$...but...
- Spacecraft size limited by launch vehicle fairing ($\sim 4m$)





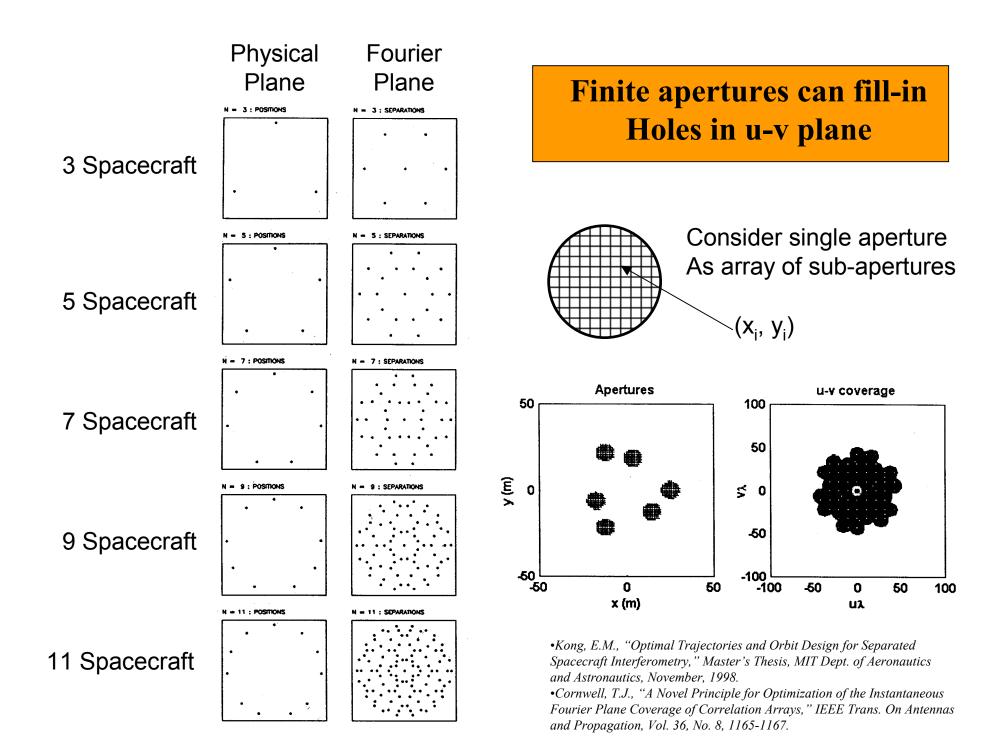
Interferometry Basics

- Spatial frequencies in the image are given by u,v points
- Each unique physical separation yields amplitude at one u,v point



Inverting Spatial Frequency \implies Spatial Amplitude \implies Image

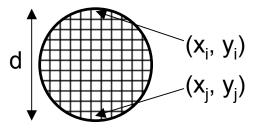
To perform the inversion we need to fill the u,v plane



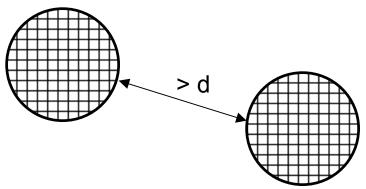


Interferometry for Formations

All separations (u,v points) less Than d are covered by a single aperture



Separations (u,v points) greater than d Must come from separated spacecraft



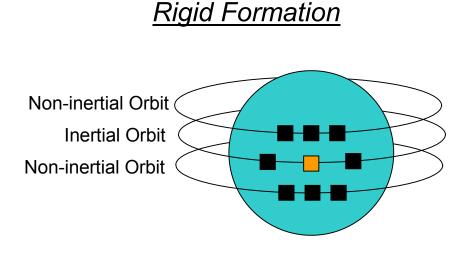
Implication:

• To provide seamless u,v coverage spacecraft must fly within close proximity (~ d) of each other



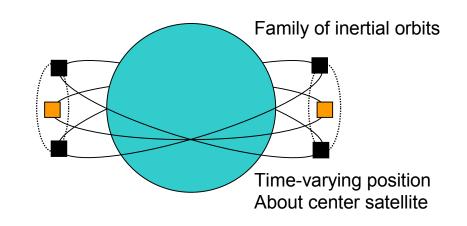
Formation Flying Introduction

Optimal imaging configurations yield non-optimal orbital trajectories



- Requires constant thrust
- Good imaging properties

Dynamic Formation



- Thrust only for error correction
- Complicated imaging



Propulsion Requirements

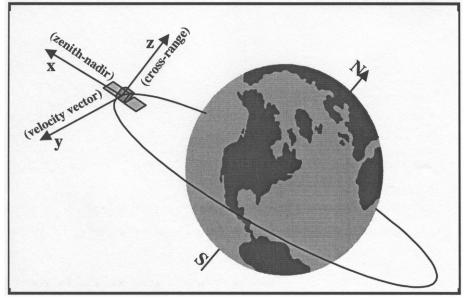
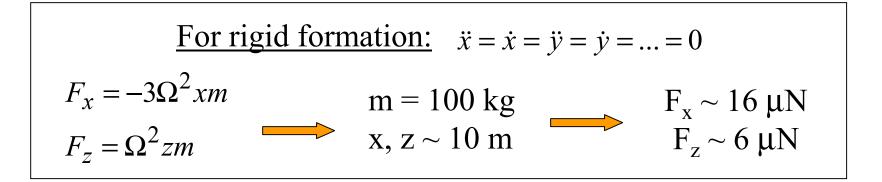


Figure reprinted from Kong, E.M., "Optimal Trajectories and Orbit Design for Separated Spacecraft Interferometry," Master's Thesis, MIT Dept. of Aeronautics and Astronautics, November, 1998.

Hill's Equations for Formation

$$\frac{F_x}{m} = \ddot{x} - 3\Omega^2 x - 2\Omega \dot{y}$$
$$\frac{F_y}{m} = \ddot{y} + 2\Omega \dot{x}$$
$$\frac{F_z}{m} = \ddot{z} + \Omega^2 z$$

 Ω = angular velocity (for GEO Ω =7.3x10⁻⁵ rad/sec)

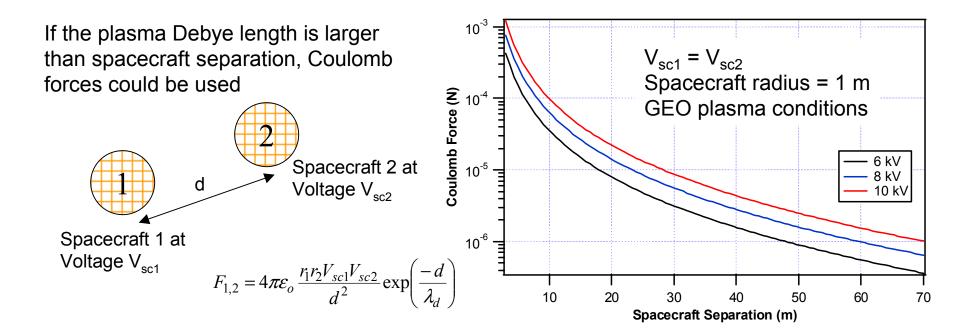




Coulomb Control Forces

- Engineering throttleable thrusters for 10 µN is tough
- Current candidates (FEEP, Colloid) exhaust contaminants
- Collisions are of paramount concern

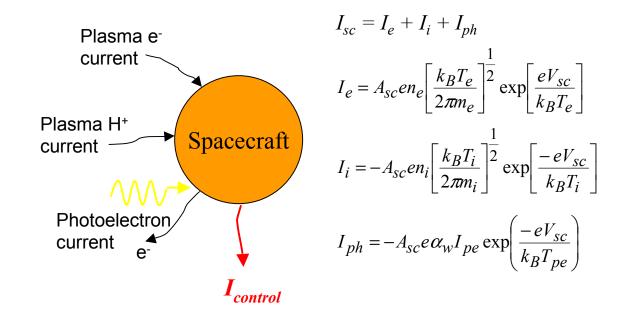
Is there a better way to control the formation? Maybe!





Spacecraft Charging

For equilibrium, Mother Nature adjusts spacecraft voltage such that net current is zero.



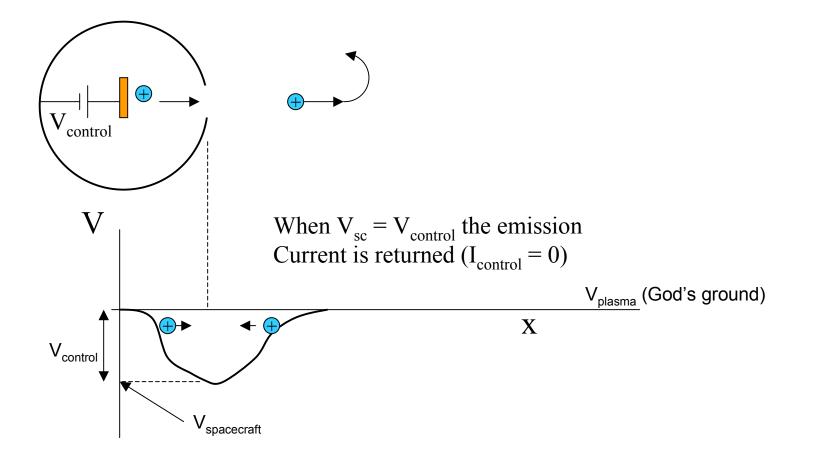
We can change the spacecraft voltage by creating a current imbalance

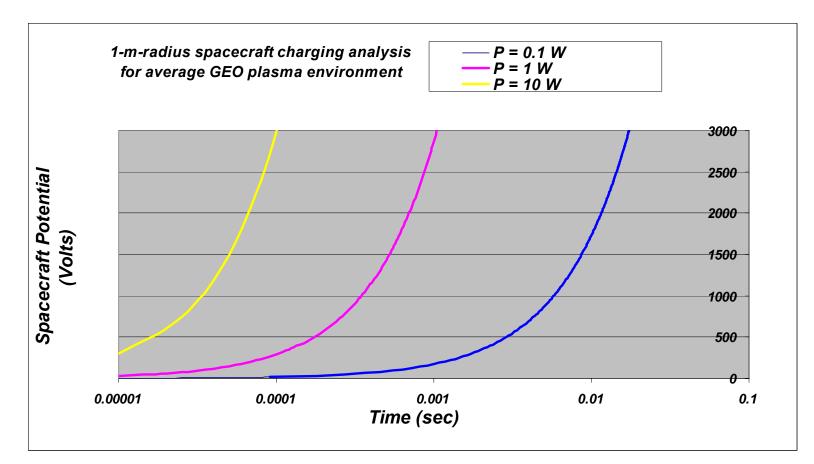
$$\frac{dV_{sc}}{dt} = \frac{I}{C} = \frac{I_e + I_i + I_{ph} + I_{control}}{4\pi\varepsilon_o r} \neq 0$$



Spacecraft Charge Control

- Electron emission drives V_{sc} positive
- Ion emission drives V_{sc} negative
- Spacecraft potential control is naturally stable



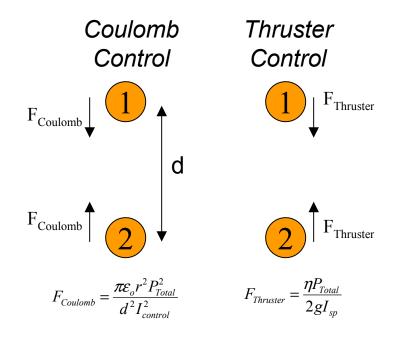


$$I_{control} = \frac{P}{V_{control}}$$

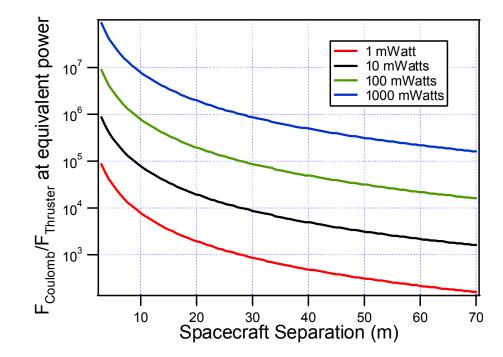
$$\frac{dV_{sc}}{dt} = \frac{I}{C} = \frac{I_{control} + 4 \pi r^{2} \left\{ en_{e} \left[\frac{k_{B}T_{e}}{2\pi m_{e}} \right]^{\frac{1}{2}} exp \left[\frac{eV_{sc}}{k_{B}T_{e}} \right] - en_{i} \left[\frac{k_{B}T_{i}}{2\pi m_{i}} \right]^{\frac{1}{2}} - e\alpha_{w}I_{ph} \right\}}{4 \pi \varepsilon_{0} r}$$



Coulomb vs. Electric Propulsion



Comparison of Coulomb Control for 1-m-radius Spacecraft in average GEO plasma with FEEP Thruster technology ($I_{sp} = 10,000$ sec, $\eta = 0.65$)





Mission design parameters for two-spacecraft flying in 20-m formation (located on Hill's z-axis)

MEANS OF CONTROL	COULOMB CONTROL	MICROPPT	COLLOID THRUSTER	FEEP
SPECIFIC IMPULSE (sec)	$1 \ge 10^7$ $I_{sp} = \frac{F}{\dot{m}g}$	500	1000	10000
EFFICIENCY	0.65	0.026	0.65	0.65
MASS OF FUEL FOR 10 YEARS (kg)	0.00003 (using H_2 for Ion source)	0.089	0.045	0.004
INPUT POWER (W)	0.031	0.261	0.021	0.209
MASS/POWER RATIO (kg/W)	0.22	0.37	0.216	0.1125
INERT MASS (kg)	0.0068	0.097	0.005	0.024
TOTAL PROPULSION SYSTEM MASS (kg)	0.00683	0.186	0.050	0.028



Coulomb Orbit Dynamics

• 3-spacecraft formations considered

• Hill's equations for relative motion

• GEO orbit with 10-m separation

• 3 canonical orientations

Do formations exist for forces acting only along position vectors?

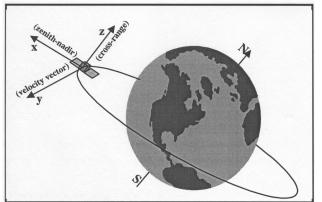
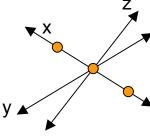


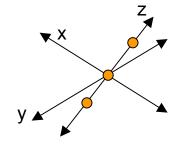
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Along-track

"leader-follower"



Zenith-nadir "Coulomb tether"

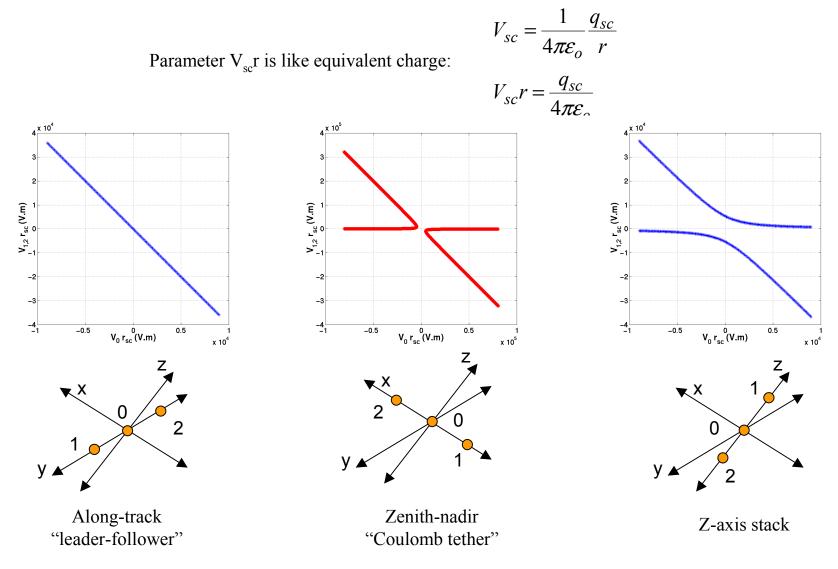


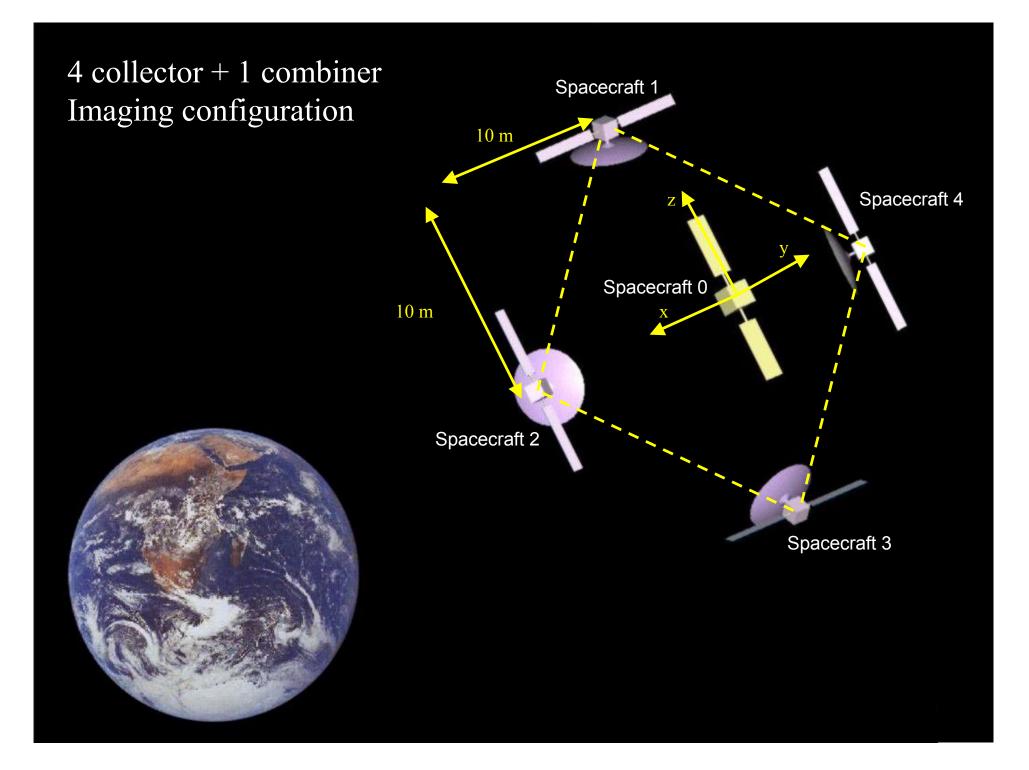
Z-axis stack



3-Spacecraft Orbital Analysis

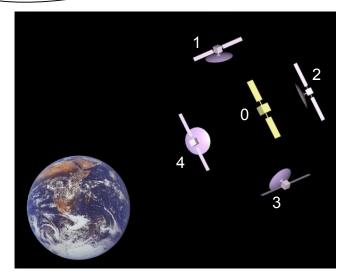
Equilibrium solutions to Hill's equations







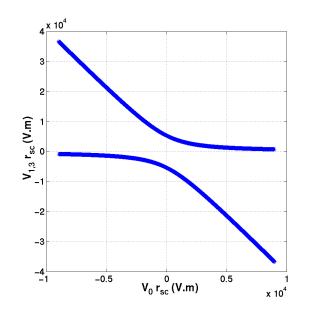
5-Spacecraft Formation



$\begin{array}{c} 1 \\ 0.8 \\ 0.6 \\ 0.4 \\ \hline 0.6 \\ 0.4 \\ \hline 0.6 \\ 0.4 \\ \hline 0.7 \\ -0.2 \\ -0.4 \\ -0.6 \\ -0.8 \\ -1 \\ -1 \\ -0.5 \\ \hline V_0 r_{sc}^{0} (V.m) \\ \hline 0.5 \\ 1 \\ x 10^4 \end{array}$

Solution Family 1

- Special case of 3-spacecraft z stack
- Vehicle 2 and 4 remain neutral

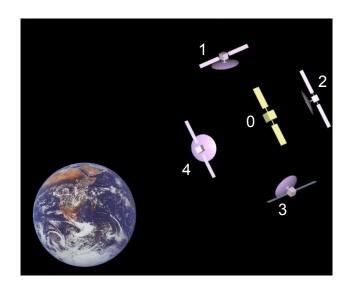


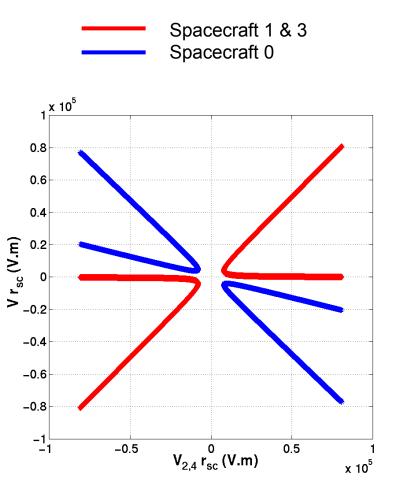


5-Spacecraft Formation

Solution Family 2

- All 5 Spacecraft charged
- Minimum V_{sc}r identified







Phase I Summary

Conclusions

- Coulomb forces comparable with best thrusters
- Continuous force dither/variation is possible
- Required charge control demonstrated as early as 1979 (SCATHA)
- Rich family of orbital solutions possible
- Particularly suited to Fizeau interferometry (visible GEO imager?)
- Coulomb control works best where thrusters work worst => synergistic control
- Coulomb control can help with collision avoidance
- Even if Coulomb is not used for control.....

natural charging will be significant perturbation that must be addressed!

On-going tasks

- Examine formations for stability
- Develop dynamic simulation
- Formulate control laws
- Search for more complicated formation solutions
- Perform vehicle sizing analysis for canonical mission