NIAC Status Report for the Kennedy Space Center

November 28, 2001





Wyn Wachhorst The Dream of Spaceflight

It is at its frontiers that a species experiences the most perturbing stress. The urge to explore, the quest of the part for the whole, has been the primary force in evolution since the first water creatures began to reconnoiter the land. We humans see this impulse as the drive to self-transcendence, the unfolding of self-awareness...

Living systems cannot remain static; they evolve or decline. They explore or expire. The inner experience of this imperative is curiosity and awe. The sense of wonder—the need to find our place in the whole—is not only the genesis of personal growth but the very mechanism of evolution, driving us to become more than we are. Exploration, evolution, and self-transcendence are but different perspectives on the same process. The visions we offer our children shape the future. It matters what those visions are. Often they become self-fulfilling prophecies. Dreams are maps.



JULES VERNE

Wyn Wachhorst, The Dream of Spaceflight

The frontier, like the world of the child, is a place of wonder explored in the act of play. Work is selfmaintenance; play is self-transcendence, probing the larger context, seeking the higher order...

Joseph Campbell has observed that in countless myths from all parts of the world the quest for fire occurred not because anyone knew what the practical uses of fire would be, but because it was fascinating. Those same myths credit the capture of fire with setting man apart from the beasts, for it was the earliest sign of that willingness to pursue fascination at great risk that has been the signature of our species. Man requires these fascinations, said the poet Robinson Jeffers, as "visions that fool him out of his limits."

Like the capture of fire, the longing for space-flight is rooted less in means than in meaning itself.



- Focus on Revolutionary Advanced Concepts for Architectures and Systems
- Be an Institute Independent of NASA
 - -- Management and guidance external to NASA
 - -- Non-NASA (mostly) peer review
 - -- NIAC issues and manages research grants/contracts
 - -- Contractually reports to GSFC with funding from NASA HQ
- Operate as a Virtual Institute over the Internet (http://www.niac.usra.edu)
 - -- Calls for proposals issued through NIAC website
 - -- Proposals only accepted electronically
 - -- All abstracts, reports, web links and presentations are available on NIAC website
- Succinct Technical Proposal Requirements and Peer Review
 - -- Phase I (12 pages), Phase II (25 pages)
 - -- Typical evaluation process, 2 2.5 months from receipt of proposal to award

'Visions of the future may affect our interpretation of and appreciation for the present. Our focus on the future turns our minds towards possibilities and away from more immediate conflicts and helps to remind us that there will be a future."

Robert A. Cassanova



Where have we been?

Where are we going?

We shall not cease from exploration And in the end of all our exploration Will be to arrive where we started And know the place for the first time. – T. S. Eliot, "Little Gidding"

NIAC Investments To-Date



NASA Institute for Advanced Concepts



- Fulfill the human desire to understand our place in the universe.
- Seek knowledge to understand how we evolved and what is our destiny.
- Search for life in the universe and understand cosmological phenomena.



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- Pursue the fascination of space and satisfy the human drive for exploration of the vastness of space, often at great risk.
- Make possible the safe, affordable and effective exploration, development and selfreliant habitation of our solar system – and eventually space beyond our solar system – by humans and their agents.
- Mediate the effects of the space environment, such as microgravity and radiation, on humans and other living things,



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- Mediate the effects of the space environment, such as microgravity and radiation, on humans and other living things,
- Provide seamlessly integrated, safe, reliable, fast and efficient transportation network from the Earth's surface to distant locations in space as well as portal to portal on the Earth's surface.

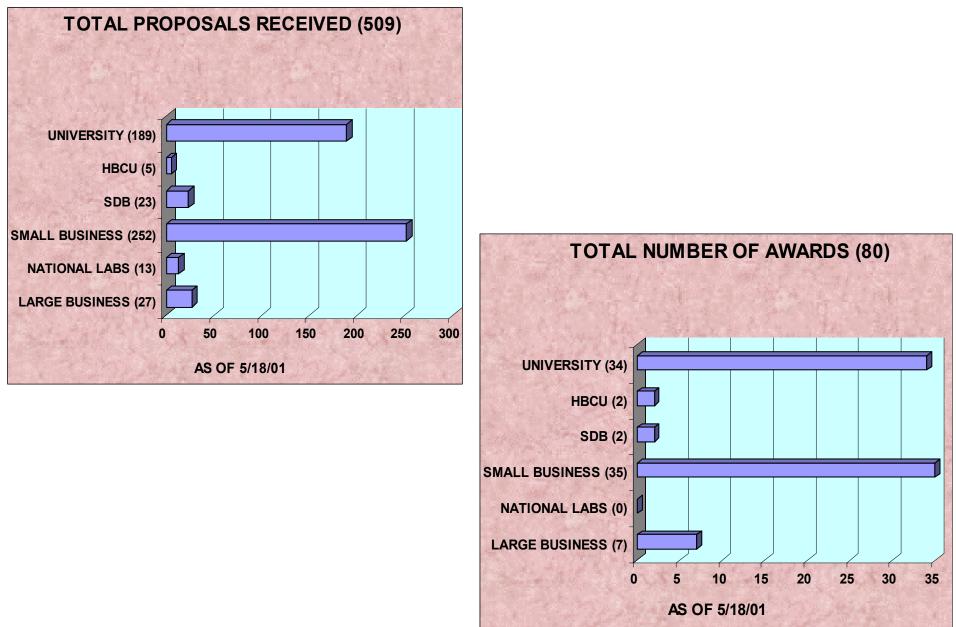


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- Understand the influence on the Earth system of the actions of mankind, the natural cyclic phenomena in the Earth's system and the interaction of the Sun-Earth system.
- Create tools and techniques to access, visualize and interpret data and model findings.
- Predict the future evolution of the Earth system and its relationship to natural phenomena and human activity, and validate this predictive capability.



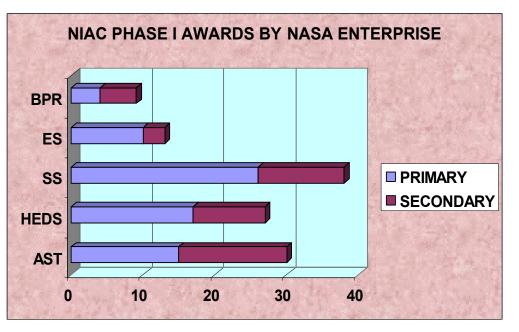
Proposals Received and Awards

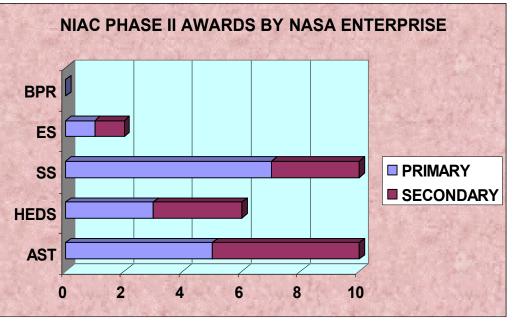
(through May 18, 2001)





NIAC Awards (through May 18, 2001)







September 2001

Release of Next Phase I Call for Proposals with a due date of early February 2002

October 30-31, 2001

NIAC Phase I Fellows Meeting and Workshop NIAC HQ, Atlanta, Georgia

November 6-7, 2001

Workshop on Revolutionary Aerospace Systems Concepts for Human/Robotic Exploration of the Solar System NASA LaRC

<u>June 4-5, 2002</u>

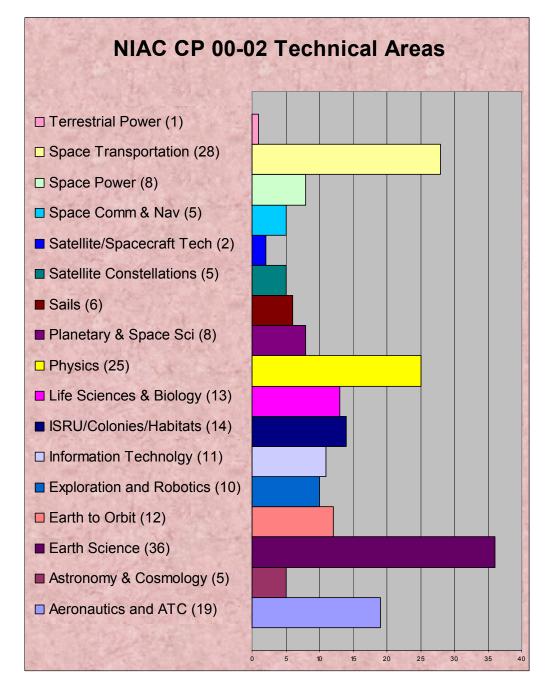
NIAC 4th Annual Meeting Lunar and Planetary Institute, Houston, Texas



Phase I Awards Call for Proposals: CP 00-02 Performance Period: June 1 – November 30, 2001



CP 00-02 Proposals

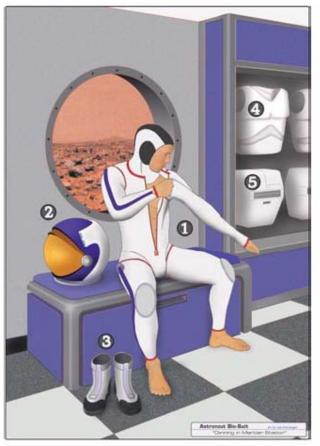


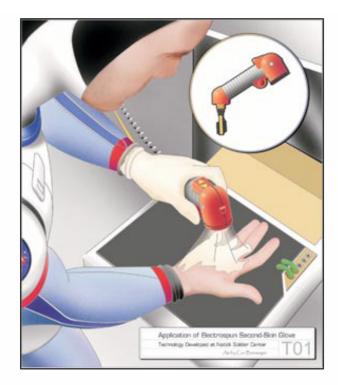
Total Proposals = 172 Some are double counted In multiple technical areas



Astronaut Bio-Suit System for Exploration Class Missions

Dava Newman, Massachusetts Institute of Technology

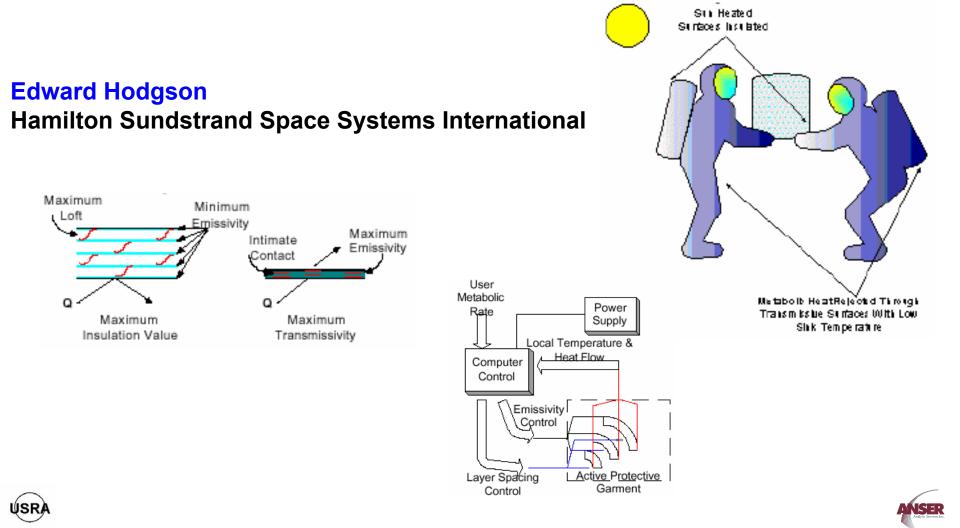




An astronaut on Mars donning the comfortable elastic bio-suit layer (1). The hard torso shell (4) is donned next and seals with couplings at the hips and shoulders. The hard backpack, or portable life support system, (5) attraches mechanically to the hard torso shell, and provides gas counter pressure. Gas pressure flows freely into the helmet (2) and down tubes on the elastic bio-suit layer to the gloves and boots (3). The bio-suit layer is lightweight and easy to don and doff. It is custom fitted to each astronaut using a laser scanning/electrospiniacing process (Natick Soldier Center). Remaining suit elements are simple, functional, interchangeable and easy to maintain and repair. Electrospinlacing is a process where a multi-filament fiber of polymer is sprayed onto a grounded surface, which is achieved by charging a suspended drop of polymer with tens of thousands of volts. At a characteristic voltage the droplet forms a Taylor cone, and a fine jet of polymer releases from the surface in response to the tensile forces generated by interaction of an applied electric field with the electrical charge carried by the jet. The projected polymer can be collected as a continuous web of fibers in a range of thicknesses. Application can be made directly to the skin as shown, or to advanced 3D forms from laser scans. Wearable computers, smart gels and conductive materials could be embedded between polymer layers in future space suit applications. Electrostrictive gel is used to create a seamless mechanical counter-pressure (MCP) layer. A simple hand-held spray device is used for self application.



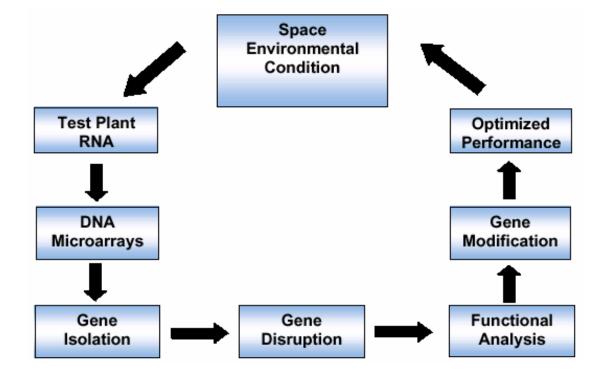
A Chameleon Suit to Liberate Human Exploration of Space Environments





A Flexible Architecture for Plant Functional Genomics in Space Environments



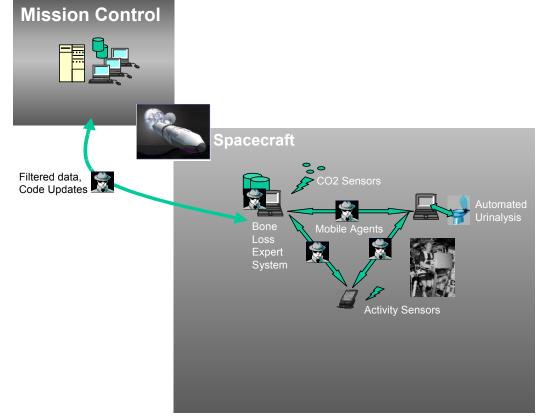








A Novel Information Management Architecture for Maintaining Long Duration Space Crews



•Agents transmit information to and from Mission Control.

- •Agents ability to analyze information prior to moving saves bandwidth.
- •Code and data can be updated throughout the mission, enabling increased performance and adaptation to mission conditions.



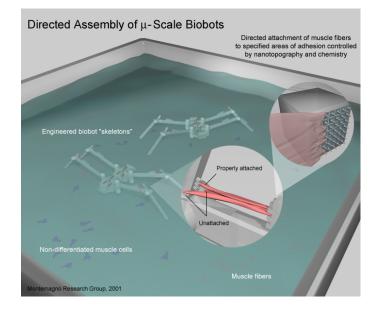
George Cybenko

Dartmouth College

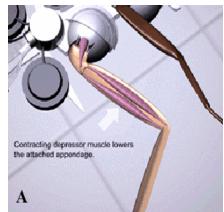


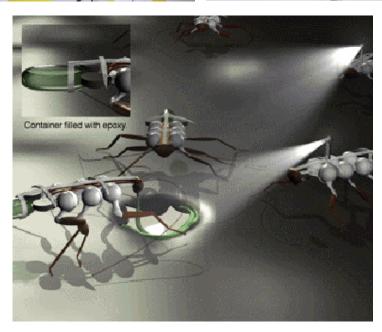
Directed Application of Nanobiotechnology for the Development of Autonomous Biobots

Carlo Montemagno Cornell University





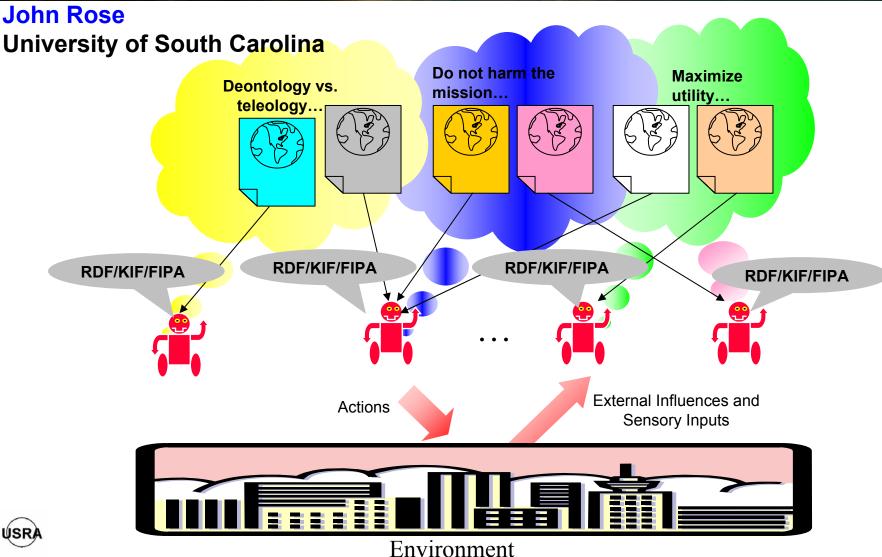








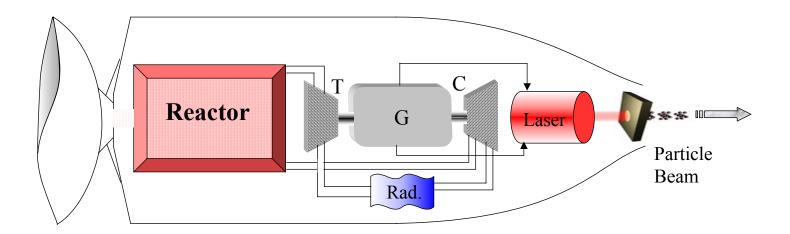
Achieving Comprehensive Mission Robustness







Terry Kammash University of Michigan



Laser-Accelerated Plasma Propulsion System (LAPPS)

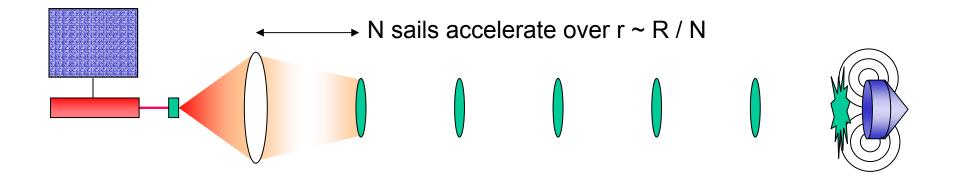






High Acceleration Micro-Scale Laser Sails for Interstellar Propulsion

Jordin Kare Kare Technical Consulting









High Speed Interplanetary Tug / Cocoon Vehicles (HITVs)

ACCELERATION PHASE **RELEASE PHASE** SPACECRAFT REACHING **JUPITER IN 30 DAYS**

Nick Omidi Scibernet, Inc.







Formation Flying with Shepherd Satellites

Michael LaPointe, Ohio Aerospace Institute



 Proposed shepherd satellite concept is based on established optical gradient force trapping techniques

• Focused electromagnetic radiation from shepsats interacts with applied dipole moments on microsats, providing electromagnetic gradient forces to position and maneuver the formation-flying array

• Individual microsats can devote their limited mass and power to instrumentation and observation



Propellantless Control of Spacecraft Swarms using Coulomb Forces

Brad King Michigan Technology University

- Potentially feasible to generate tens of micro-Newtons of attraction and repulsion between spacecraft separated by tens of meters.
- Net spacecraft charge can be controlled by harvesting ambient space-plasma electrons or actively emitting electrons.
- Mutually interacting Coulomb spacecraft will be oriented in stable minimum energy arrays that can be configured using active control.
- Advantages
 - Circumvent need for micro-thrusters in satellite swarms
 - Increase formation mission lifetimes by harvesting in-space resources
 - Greatly improve fine position-keeping through active feedback
 - Facilitate wider range of satellite formation
 - Increase swarm robustness through fault-detection and reconfiguration

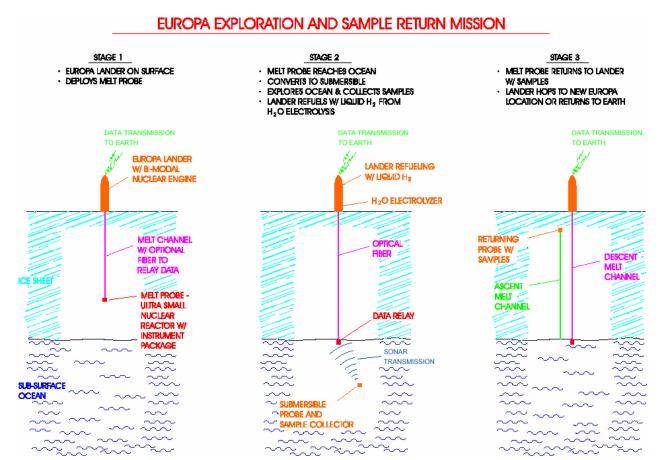






Europa Sample Return Mission utilizing High Specific Impulse Propulsion Refueled with Indigenous Resources

John Paniagua Plus Ultra Technologies, Inc.



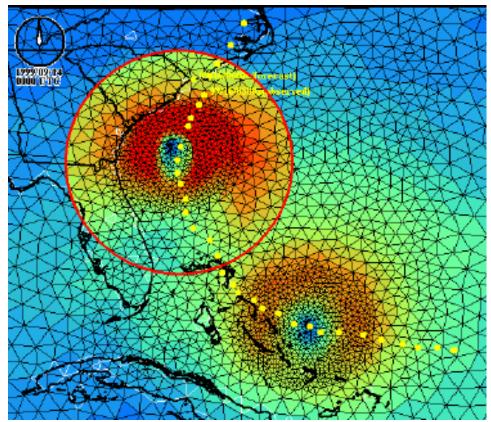




Adaptive Observation Strategies for Advanced Weather Prediction

David Bacon SAIC, Center for Atmospheric Physics

Michael Kaplan North Carolina State University



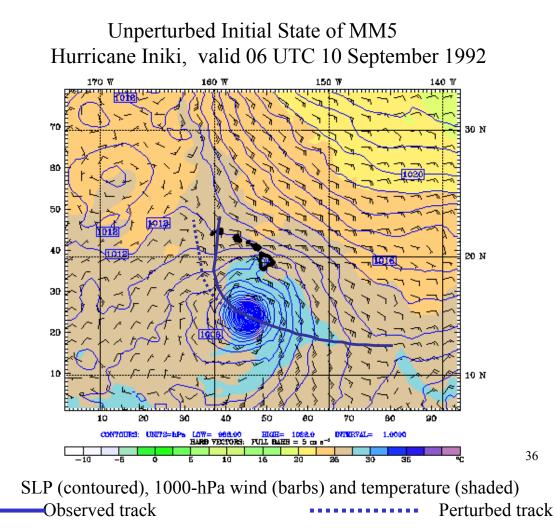








Ross Hoffman, Atmospheric and Environmental Research, Inc.

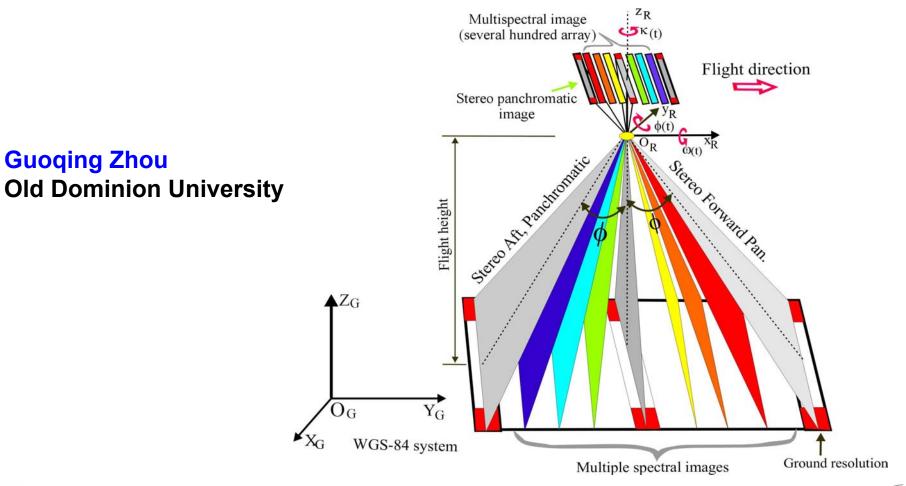








Architecture of "Intelligent" Earth Observation Satellite for Common Users in 2010-2050

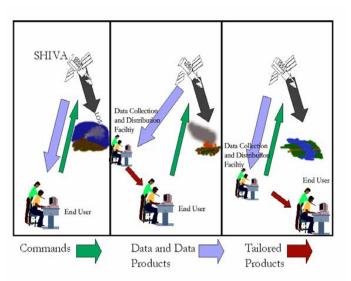




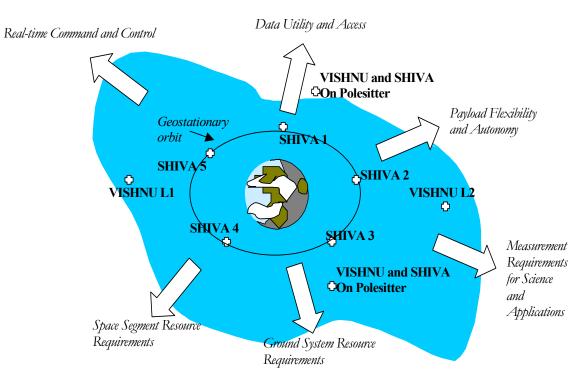


Global Observations and Alerts from Lagrange-Point, Pole-Sitter, and Geosynchronous Orbits (GOAL&GO)

Larry Paxton Johns Hopkins University Applied Physics Laboratory



The SHIVA system uses multiple, selectable bands as commanded by remotely located users to search for, identify, and report geophysical events. A pointed telemetry system reduces the ground system requirements.









3D Viewing of Images on the Basis of 2D Images

H. John Caulfield Fisk University

- Analogous to how nature allows you to see a 3D image using only one eye at a hyperfocal distance from your eye
- Connected set of computer programs that start with any digitized 2D image and convert it into a pair of images for 3D visualization
- Will be tested on telescopic and microscopic images in Phase I
- · Feasibility established for simple objects in the near field
- Will record simulated scenes of interest for NASA and blur them by various amounts digitally to simulate telescopic images
- · Attempt 3D visualization of local regions
- Design software for a hardware system to be built in Phase II





Ultra-High Resolution X-ray Astronomy using Steerable Occulting Satellites

Glenn Starkman Case Western Reserve University

- Occultation of an X-ray telescope by a steerable satellite may allow binary point source resolution better than milli-arcsecond with little or no re-design of X-ray telescopes.
- Model reconstructive capabilities of the technique and adjust satellite shape so as to maximize those capabilities.
- Evaluate possible scientific payback from implementing this approach in conjunction with planned facilities, such as Constellation-X.
- · Occulter design considerations to be investigated.
 - Thickness
 - Size
 - Steerability
 - Binary point source resolution
 - Compound source resolution
 - Target sources



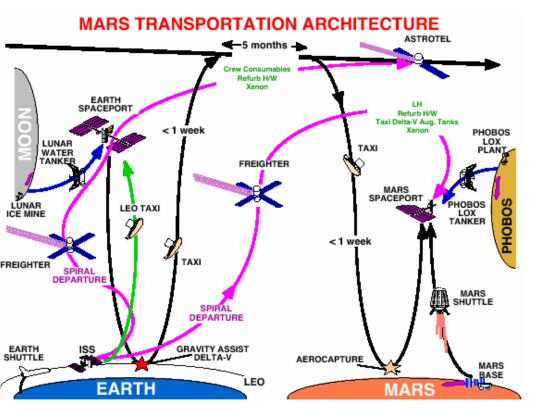


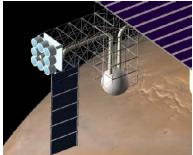


Phase II Awards Calls for Proposals: CP 99-01, CP 99-02, CP 00-02



Cyclical Visits to Mars via Astronaut Hotels Kerry Nock, Global Aerospace Corporation Phase II Performance Period: March 1, 2001 to January 31, 2003





Astrotel IPS





Taxi departing



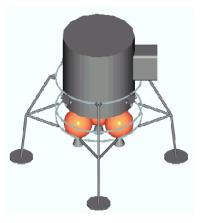
Taxi during Mars Aerocapture

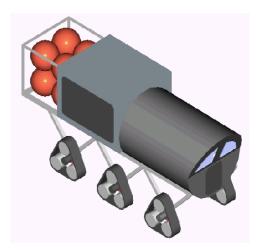






Advanced System Concept for Total ISRU-Based Propulsion and Power Systems for Unmanned and Manned Mars Exploration Eric Rice, Orbital Technologies Corporation Phase II Performance Period: April 1, 2000 to March 31, 2002



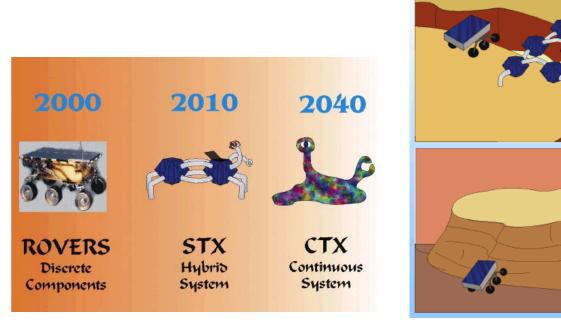


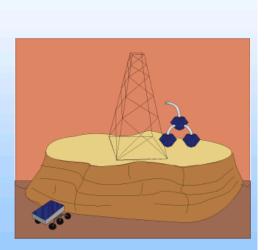


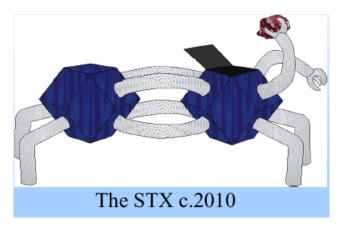




Self-Transforming Robotic Planetary Explorers Steven Dubowsky, Massachusetts Institute of Technology Phase II Performance Period: September 1, 1999 to August 31, 2001





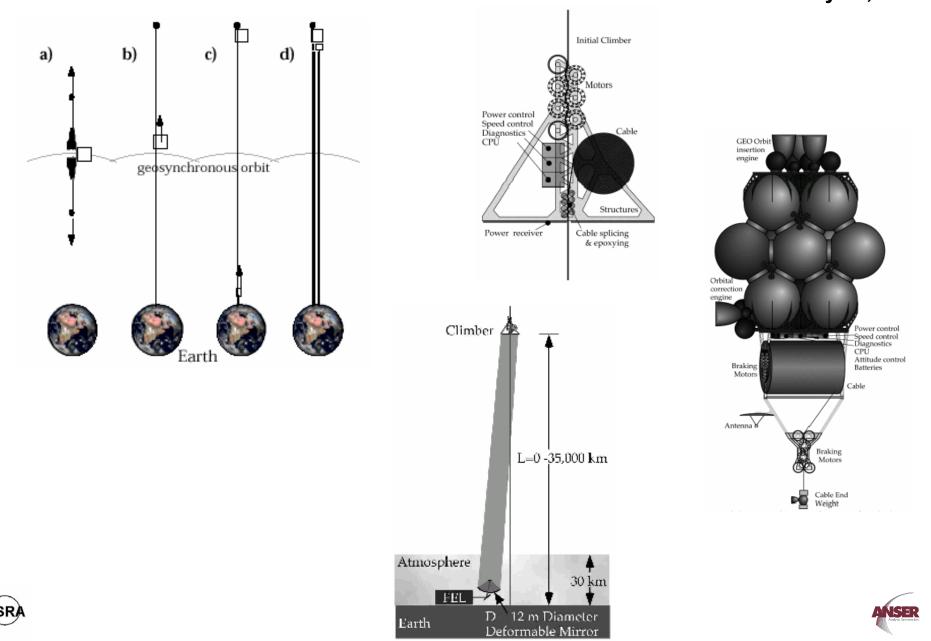






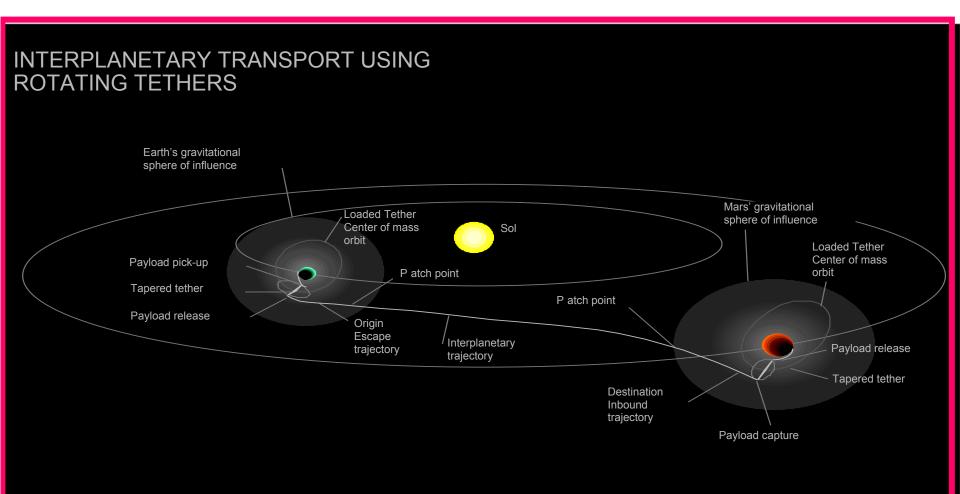


The Space Elevator Bradley Edwards, Eureka Scientific Phase II Performance Period: March 1. 2001 to January 31, 2003





Moon and Mars Orbiting Spinning Tether Transport (MMOSTT) Robert P. Hoyt, Tethers Unlimited, Inc. Phase II Performance Period: August 1, 1999 to July 31, 2001

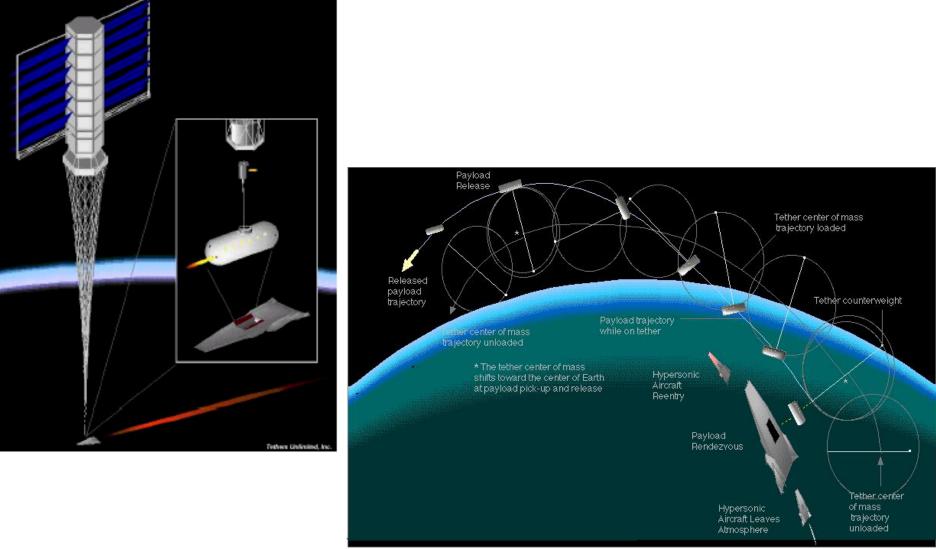






Hypersonic Airplane Space Tether Orbital Launch – HASTOL

John Grant, The Boeing Company Phase II Performance Period: April 1, 2000 to September 30, 2001



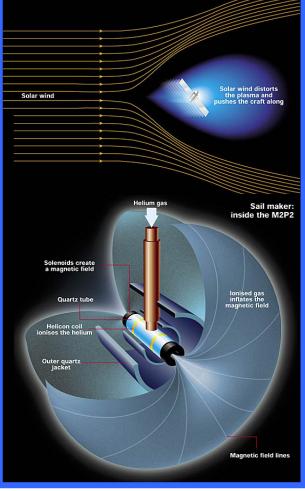




*The Mini-Magnetospheric Plasma Propulsion System, M*²*P*² Robert M. Winglee, University of Washington Phase II Performance Period: August 1, 1999 to July 31, 2001



Concept for interstellar propulsion and radiation shielding

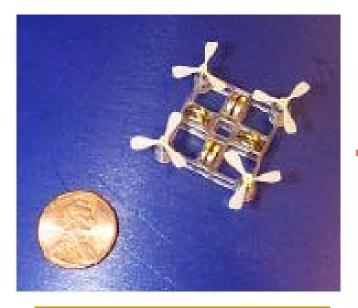


Graphics by permission of *New Scientist*





Meso-Scale Flight Vehicle for Atmospheric Sensing Ilan Kroo, Stanford University Phase II Performance Period: August 1, 1999 to July 31, 2001



The Concept: Applications

Atmospheric Studies

- Windshear, turbidence monitors
- Biological/chemical hazard detection

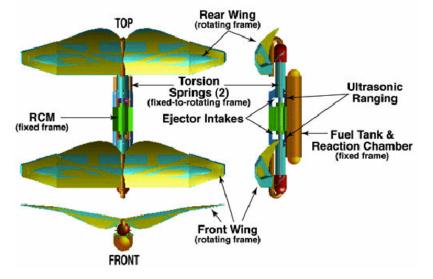
Planetary Atmospherics

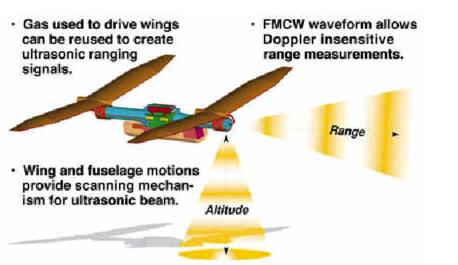
 Swarms of low-mass mobile robots for unique data on Mars

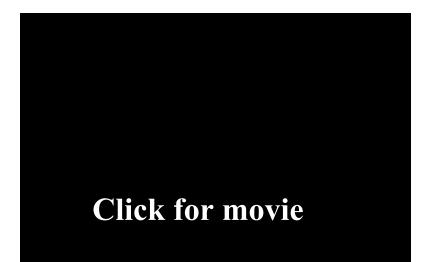




Planetary Exploration Using Biomimetrics Anthony Colozza, Ohio Aerospace Institute Phase II Performance Period: March 31, 2001 to August 31, 2002



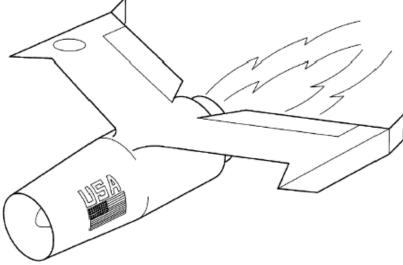




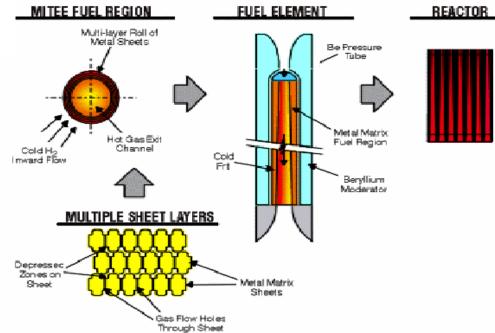




Exploration of Jovian Atmosphere Using Nuclear Ramjet Flyer George Maise, Plus Ultra Technologies, Inc. Phase II Performance Period: March 1, 2001 to January 31, 2003



MITEE Nuclear Engine

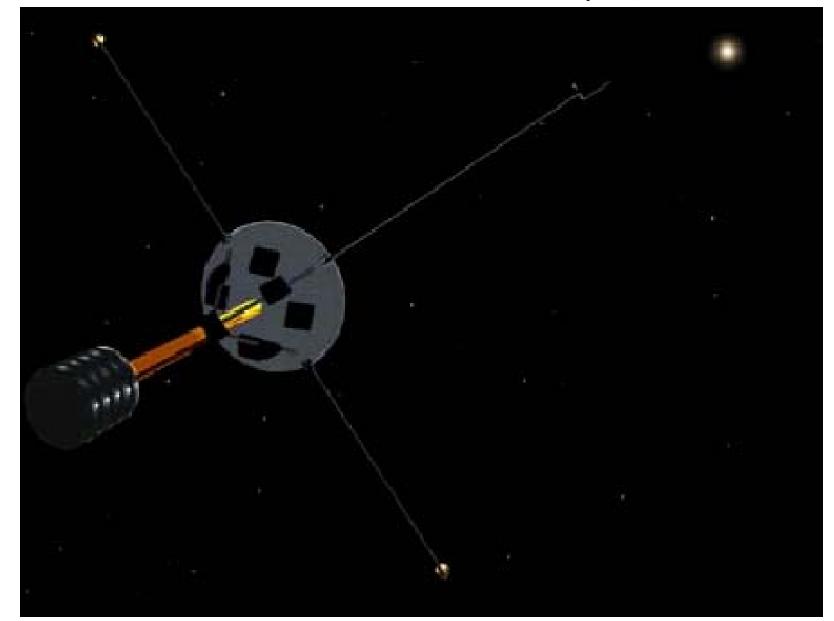








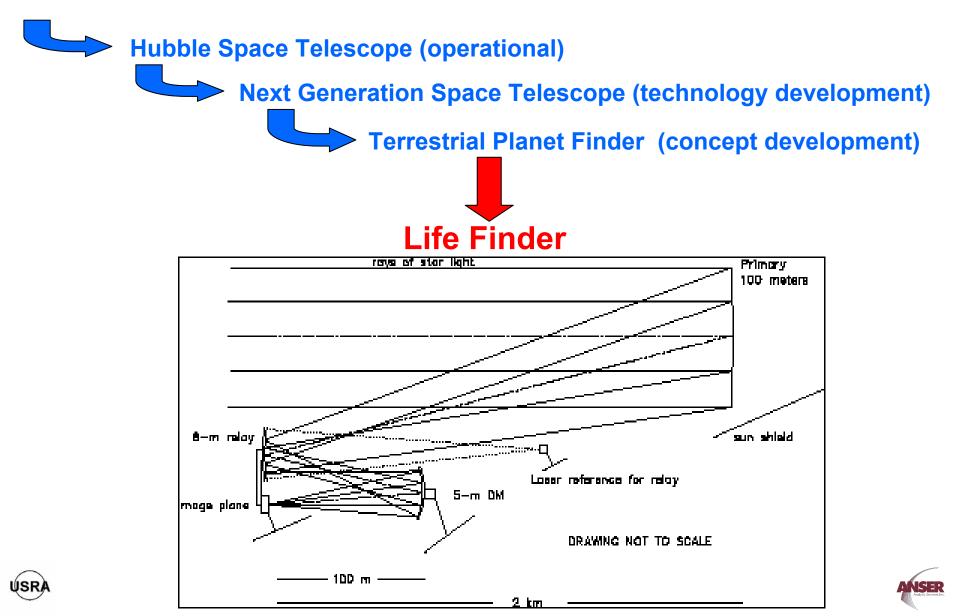
A Realistic Interstellar Explorer Ralph McNutt, Jr., Johns Hopkins Applied Physics Lab Phase II Performance Period: April 1, 2000 to March 31, 2002





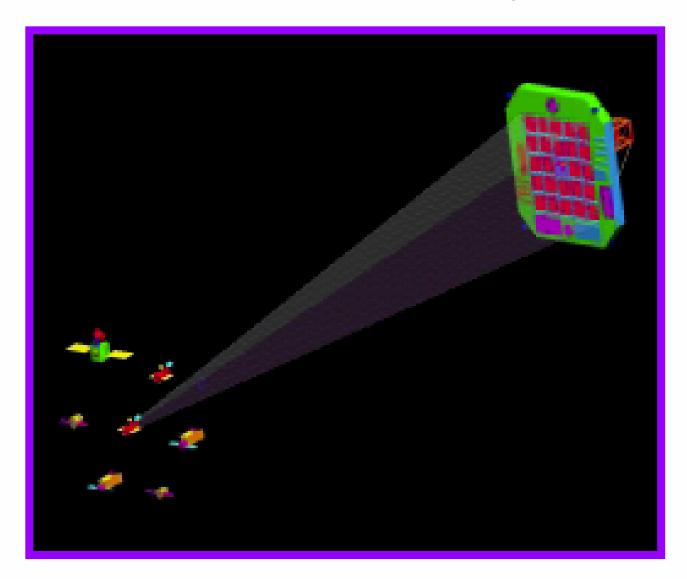


Very Large Optics for the Study of Extrasolar Terrestrial Planets Neville J. Woolf, Steward Observatory, University of Arizona Phase II Performance Period: August 1, 1999 to July 31, 2001





An Ultra-High Throughput X-Ray Astronomy Observatory with A New Mission Architecture Paul Gorenstein, Smithsonian Institute, Astrophysical Observatory Phase II Performance Period: August 1. 1999 to July 31, 2001



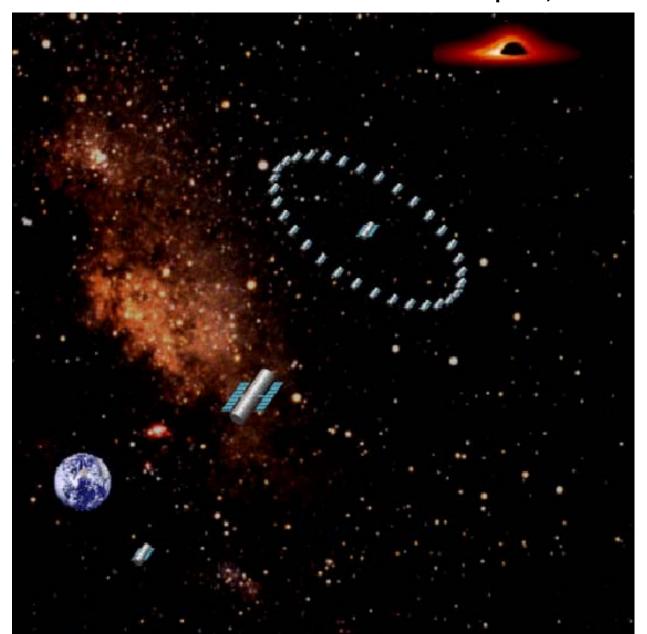






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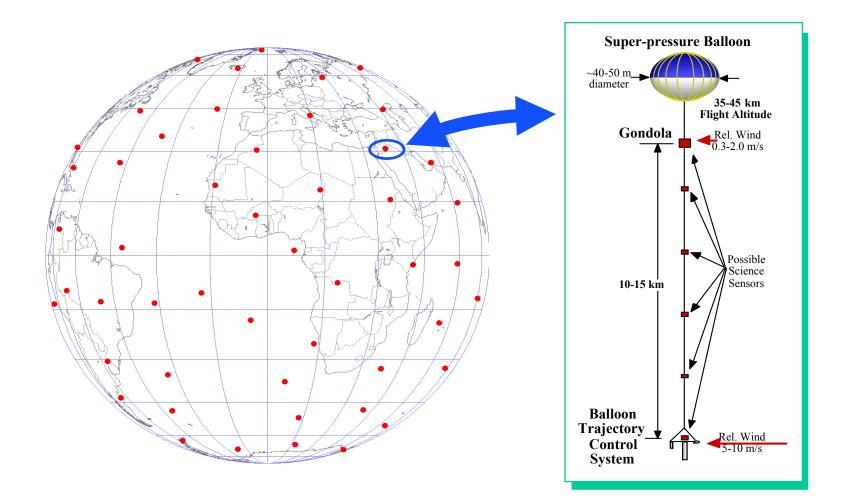
X-ray Interferometry - Ultimate Astronomical Imaging Webster Cash, University of Colorado Phase II Performance Period: April 1, 2000 to March 31, 2002







Global Constellation of Stratospheric Scientific Platforms Kerry Nock, Global Aerospace Corporation Phase II Performance Period: April 1, 2000 to February 28, 2002

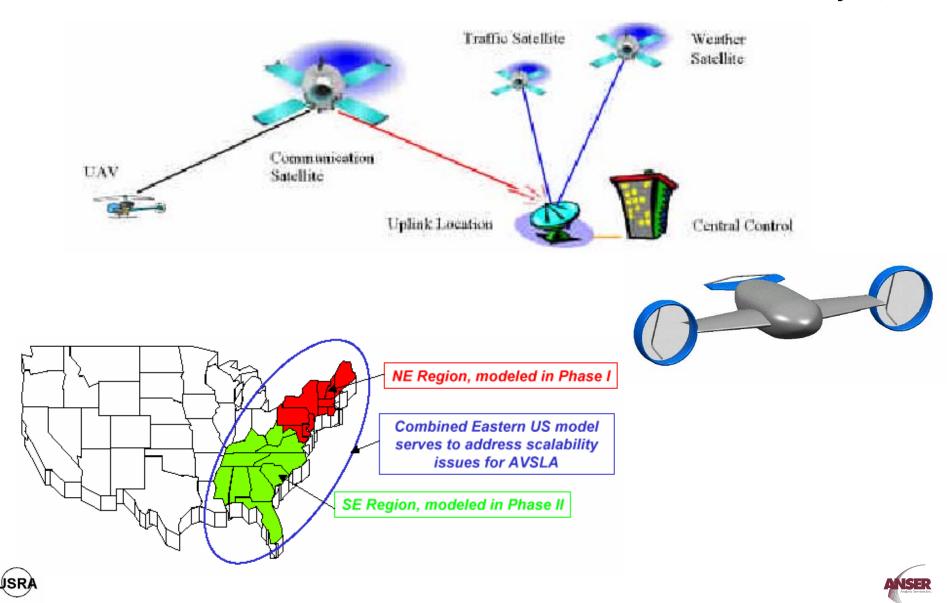








Methodology for Study of Autonomous VTOL Scalable Logistics Architecture Andrew Keith, Sikorsky Aircraft Corporation Phase II Performance Period: March 1, 2001 to January 31, 2003





Human/Robotic Exploration of the Solar System Sponsored by RASC Activity at NASA LaRC through ICASE

New task

Funded from the LaRC RASC activity through the USRA ICASE contract. Led by ICASE with NIAC involvement in the RFI and Workshop

• Human & Robotics Exploration Mission Objective:

Identify key revolutionary technologies for Human and Robotics systems which have the potential, when synergistically combined, to reduce the time, distance and safety barriers associated with scientific exploration beyond Low Earth Orbit (LEO)

• Activities:

- 1. Orchestrate a collaborative effort of industrial, government and academic experts.
- Determining the appropriate mix of autonomous systems, and crewed systems necessary to yield the greatest scientific benefits from the destination at which the systems will be deployed.
- 3. Global survey of both the human and robotic exploration activities in NASA, and elsewhere, to determine how this mix might evolve with the incorporation of revolutionary advanced systems concepts to achieve a maximum of scientific return.
- 4. Conduct a NIAC-Style Request for Information (RFI), due September 24, 2001
- 5. Organize and lead a workshop, November 6-8, 2001 at NASA LaRC
- 6. Identify key technologies that should be pursued.